Description

The DZXRALTE-008L080 digital servo drive is designed to drive brushed and brushless servomotors from a compact form factor ideal for embedded applications. This fully digital drive operates in torque, velocity, or position mode and employs Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, this drive features dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

The DZXRALTE-008L080 features a RS-232 interface for drive configuration and setup as well as a RS-485 interface for drive networking. Drive commissioning is accomplished using DriveWare® 7, available for download at www.a-m-c.com. All drive and motor parameters are stored in non-volatile memory.

The DZXRALTE-008L080 conforms to the following specifications and is designed to the Environmental Engineering Considerations as defined in MIL-STD-810F.

Power Range

Peak Current	8 A (5.7 A_{RMS})
Continuous Current	4 A (2.8 A_{RMS})
Supply Voltage	10 - 80 VDC

-40°C / -40°F — Extended Environment — +75°C / +167°F

Extended Environment Performance

Ambient Temperature	-40°C to +75°C (-40°F to +167°F)
Storage Temperature	-50°C to +100°C (-58°F to +212°F)
Thermal Shock	-40°C to +75°C (-40°F to +167°F) in 2 min.
Relative Humidity	0 to 95% Non-Condensing
Vibration	30 Grms for 5 min. in 3 axes

Features

- Four Quadrant Regenerative Operation
- Space Vector Modulation (SVM) Technology
- Fully Digital State-of-the-art Design
- Programmable Gain Settings
- Fully Configurable Current, Voltage, Velocity and Position Limits
- PIDF Velocity Loop
- PID + FF Position Loop
- Compact Size, High Power Density
- 12-bit Analog to Digital Hardware
- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching

MODES OF OPERATION
- Current
- Hall Velocity
- Position
- Velocity

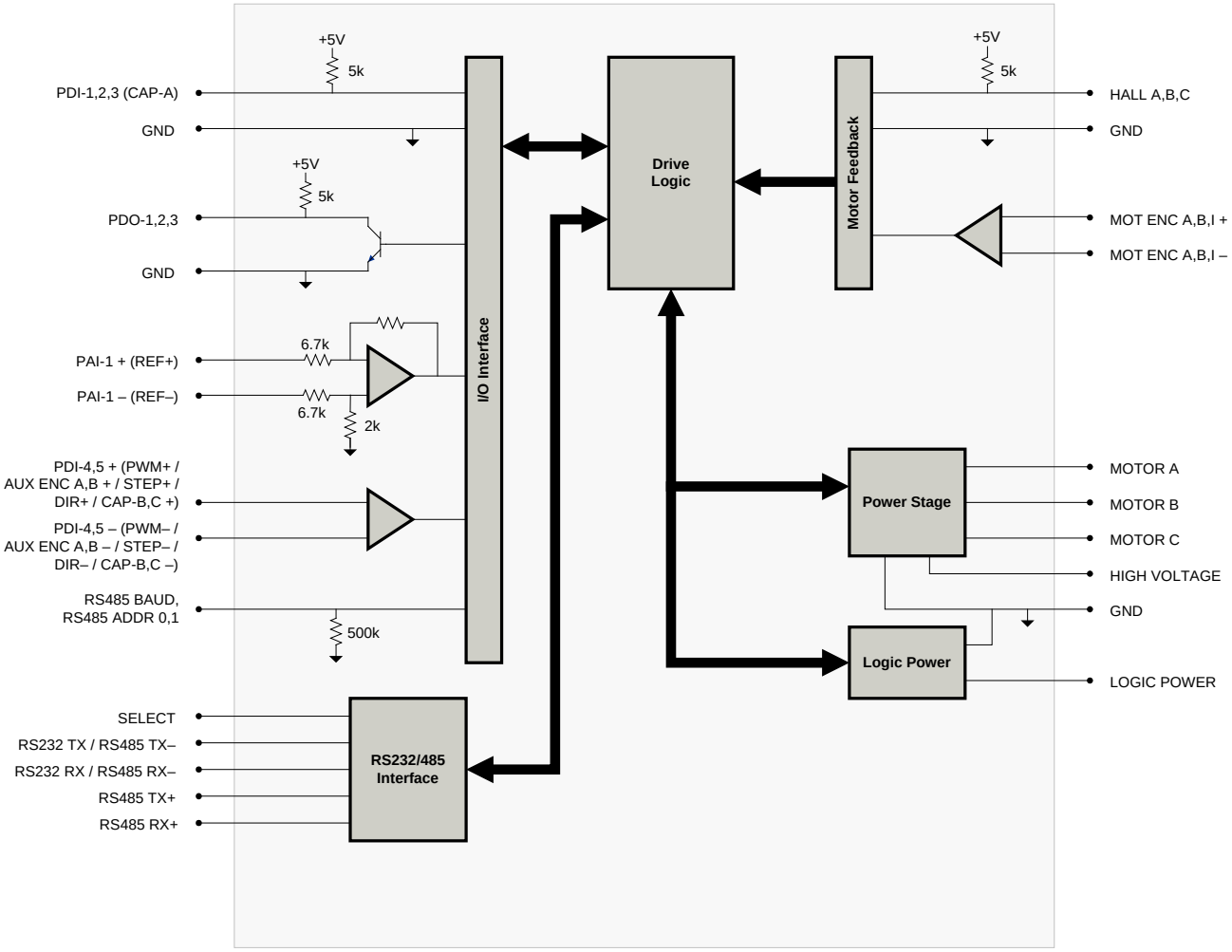
COMMAND SOURCE
- PWM and Direction
- Encoder Following
- Over the Network
- ±10 V Analog
- 5V Step and Direction
- Indexing
- Jogging

FEEDBACK SUPPORTED
- Halls
- Incremental Encoder
- ±10 VDC Position
- Auxiliary Incremental Encoder

INPUTS/OUTPUTS
- 2 High Speed Captures
- 1 Programmable Analog Input (12-bit Resolution)
- 2 Programmable Digital Inputs (Differential)
- 3 Programmable Digital Inputs (Single-Ended)
- 3 Programmable Digital Outputs (Single-Ended)

AGENCY APPROVALS & COMPLIANCE CONSIDERATIONS
- RoHS
- MIL-STD-810F (as stated)
- MIL-STD-1275D (optional)
- MIL-STD-461E (optional)
- MIL-STD-704F (optional)
- MIL-HDBK-217 (optional)
- UL Pending
- CE Pending

BLOCK DIAGRAM



Information on Approvals and Compliances	
MIL-STD-810F	Environmental Engineering Considerations and Laboratory Tests – (as stated)
MIL-STD-1275D	Characteristics of 28 Volt DC Electrical Systems in Military Vehicles – (optional)
MIL-STD-461E	Requirements for the Control of Electromagnetic Interference Characteristics of Subsystems and Equipment – (optional)
MIL-STD-704F	Aircraft Electric Power Characteristics – (optional)
MIL-HDBK-217	Reliability Prediction of Electronic Equipment (MTBF) – (optional)
RoHS COMPLIANCE	RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

SPECIFICATIONS

Power Specifications		
Description	Units	Value
DC Supply Voltage Range	VDC	10 - 80
DC Bus Over Voltage Limit	VDC	88
DC Bus Under Voltage Limit	VDC	8
Logic Supply Voltage	VDC	5 (+/- 5%)
Maximum Peak Output Current[1]	A (Arms)	8 (5.7)
Maximum Continuous Output Current	A (Arms)	4 (2.8)
Maximum Continuous Output Power	W	304
Maximum Power Dissipation at Continuous Current	W	16
Internal Bus Capacitance[2]	µF	20
Minimum Load Inductance (Line-To-Line)[3]	µH	250
Switching Frequency	kHz	20
Maximum Output PWM Duty Cycle	%	92
Control Specifications		
Description	Units	Value
Communication Interfaces	-	RS-485/232
Command Sources	-	±10 V Analog, 5V Step and Direction, Encoder Following, Over the Network, PWM and Direction, Indexing, Jogging
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Halls, Incremental Encoder
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current, Hall Velocity, Position, Velocity
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	5/3
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	1/0
Primary I/O Logic Level	-	5V TTL
Current Loop Sample Time	µs	50
Velocity Loop Sample Time	µs	100
Position Loop Sample Time	µs	100
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	RoHS, MIL-STD-810F (as stated), MIL-STD-1275D (optional), MIL-STD-461E (optional), MIL-STD-704F (optional), MIL-HDBK-217 (optional), UL Pending, CE Pending
Size (H x W x D)	mm (in)	63.5 x 50.8 x 22.9 (2.5 x 2 x 0.9)
Weight	g (oz)	105 (3.7)
Baseplate Operating Temperature Range[4]	°C (°F)	-40 - 85 (-40 - 185)
Ambient Temperature Range	°C (°F)	-40 - 75 (-40 - 167)
Storage Temperature Range	°C (°F)	-50 - 100 (-58 - 212)
Thermal Shock	°C (°F)	-40 - 75 (-40 - 167) in 2 minutes
Vibration	Grms	30 for 5 minutes in 3 axes
Relative Humidity	-	0 - 95% Non-Condensing
Cooling System	-	Natural Convection
Form Factor	-	PCB Mounted
P1 Connector	-	30-pin, 2.54 mm spaced, dual-row header
P2 Connector	-	24-pin, 2.54 mm spaced, dual-row header

Notes

1. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
2. It is recommended to connect a 100µF / 100V electrolytic capacitor between High Voltage and Power Ground.
3. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
4. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

P1 - Signal Connector			
Pin	Name	Description / Notes	I/O
1	RS485 ADDR 0	RS-485 Network Address Selector	I
2	RS485 ADDR 1		I
3	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (12-bit Resolution)	I
4	PAI-1 - (REF-)		I
5	GND	Ground	GND
6	RS485 BAUD	RS-485 Baud Rate Selector	I
7	PDO-1	Programmable Digital Output	O
8	PDO-2	Programmable Digital Output	O
9	PDO-3	Programmable Digital Output	O
10	PDI-1	Programmable Digital Input	I
11	PDI-2	Programmable Digital Input	I
12	PDI-3 (CAP-A)	Programmable Digital Input or High Speed Capture	I
13	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I
14	RS485 RX+	Receive Line (RS-485)	I
15	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	O
16	RS485 TX+	Transmit Line (RS-485)	O
17	PDI-4 + (PWM+ / STEP+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Step+ or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals see DZ HW Installation Manual)	I
18	PDI-4 - (PWM- / STEP- / AUX ENC A- / CAP-B-)		I
19	PDI-5 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals see DZ HW Installation Manual)	I
20	PDI-5 - (DIR- / AUX ENC B- / CAP-C-)		I
21	GND	Ground	GND
22	HALL A	Single-ended Commutation Sensor Input (For Differential Inputs See MC1XDZ01 Datasheet For Recommended Signal Conditioning)	I
23	HALL B		I
24	HALL C		I
25	MOT ENC I+	Differential Encoder Index Input (See MC1XDZ01 Datasheet For Recommended Signal Conditioning)	I
26	MOT ENC I-		I
27	MOT ENC A+	Differential Encoder A Channel Input (See MC1XDZ01 Datasheet For Recommended Signal Conditioning)	I
28	MOT ENC A-		I
29	MOT ENC B+	Differential Encoder B Channel Input (See MC1XDZ01 Datasheet For Recommended Signal Conditioning)	I
30	MOT ENC B-		I

P2 - Power Connector				
Pin		Name	Description / Notes	I/O
1a		LOGIC PWR	Logic Supply Input	I
	1b	RESERVED	Reserved	-
2a	2b	GND	Ground	GND
3a	3b	GND		GND
4a	4b	HIGH VOLTAGE	DC Power Input. 3A Continuous Current Rating Per Pin. 100µF, 100V external capacitor recommended between High Voltage and Ground.	I
5a	5b	HIGH VOLTAGE		I
6a	6b	RESERVED	Reserved	-
7a	7b	MOTOR C	Motor Phase C. 3A Continuous Current Rating Per Pin.	O
8a	8b	MOTOR C		O
9a	9b	MOTOR B	Motor Phase B. 3A Continuous Current Rating Per Pin.	O
10a	10b	MOTOR B		O
11a	11b	MOTOR A	Motor Phase A. 3A Continuous Current Rating Per Pin.	O
12a	12b	MOTOR A		O

Pin Details

RS485 ADDR 0 (P1-1)

This pin, RS485 ADDR 0, as well as RS485 ADDR 1, are used for RS-485 network addressing. To set the address of a drive, use the formula

$$RS485Address = \frac{7 * Addr0}{3} + 8 * \frac{7 * Addr1}{3},$$

where *RS485Address* is the desired node address and *Addr0* and *Addr1* represent the voltage that should be applied to pins RS485 ADDR 0 and RS485 ADDR 1, respectively. The values for *Addr0* and *Addr1* are always integer multiples of 3/7 V within the range 0-3 V. Examples of the voltages required to set certain node addresses are given in the table below. Note that setting a drive address of 0 will utilize the address stored in non-volatile memory.

RS485 ADDR 0 Value (V)	RS485 ADDR 1 Value (V)	RS485 ADDR Tolerance (V)	RS485 Address (Address #)
0	0	±0.1	Address stored in non-volatile memory
3/7 (0.43)	0	±0.1	1
6/7 (0.86)	0	±0.1	2
9/7 (1.3)	0	±0.1	3
…	…	±0.1	…
18/7 (2.57)	21/7 (3.0)	±0.1	62
21/7 (3.0)	21/7 (3.0)	±0.1	63

RS485 BAUD (P1-6)

The RS-485 baud rate is set by applying the appropriate voltage to the RS485 BAUD pin as given in the table below.

RS485 BAUD Value (V)	RS485 BAUD Tolerance (V)	RS485 Baud Rate (bits/s)
0	±0.388	Bit rate stored in non-volatile memory
1	±0.388	9.6k
2	±0.388	38.4k
3	±0.388	115.2k

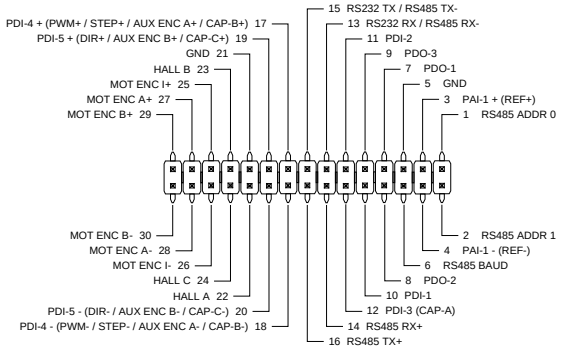
HARDWARE SETTINGS

Jumper Settings

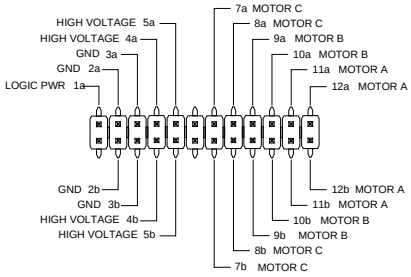
Jumper	Description	Configuration		
	Header Jumper	Not Installed	Pins 1-2	Pins 2-3
J1	Reserved.	-	-	N/A
J2	Reserved.	-	-	N/A
J3	RS-485 selection. Install this jumper (2mm) to select RS-485 communication. This jumper is located on a 6-pin header between the PCB and heatsink. It consists of the two pins closest to the corner of the PCB.	RS-232	RS-485	N/A

MECHANICAL INFORMATION

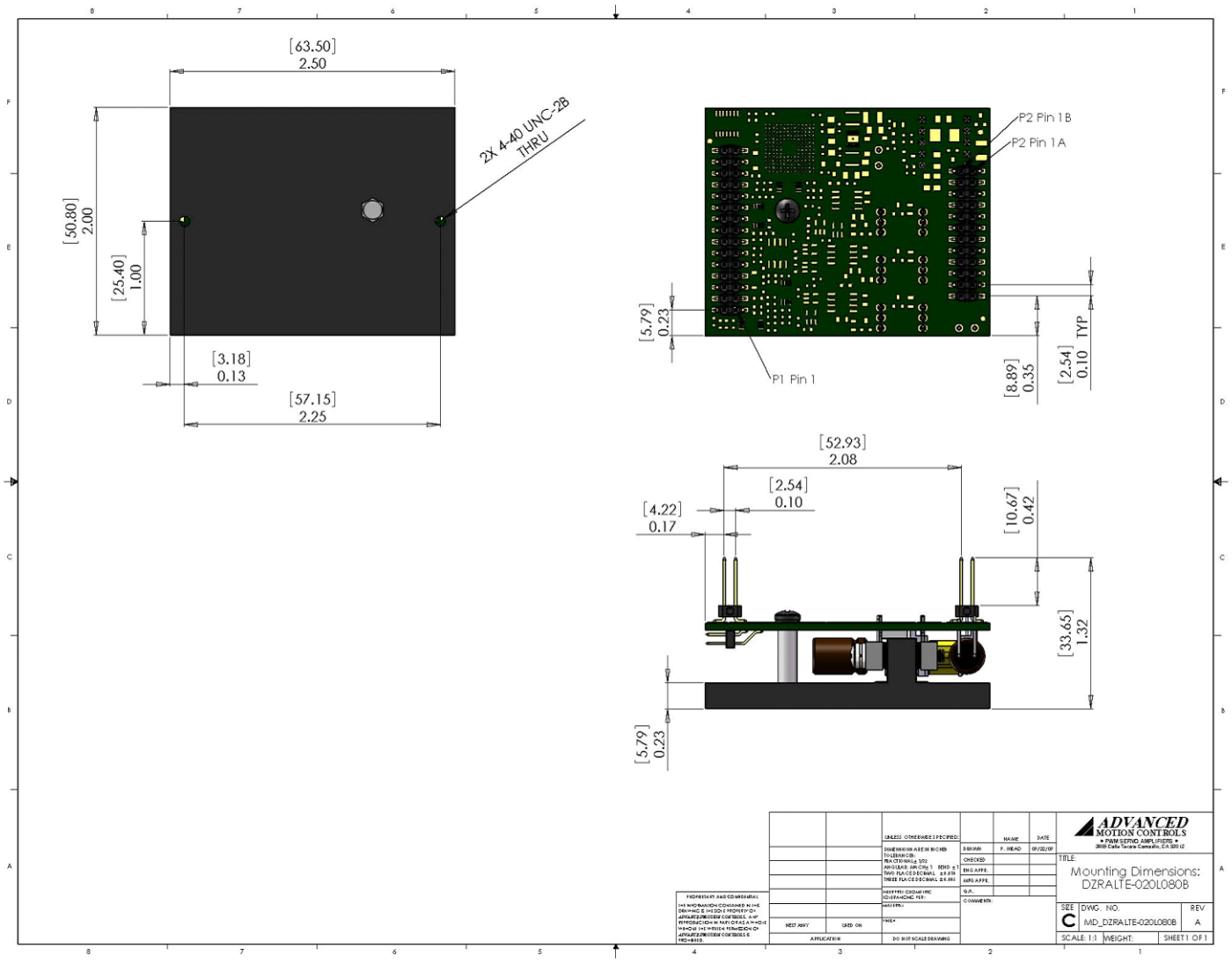
P1 - Signal Connector		
Connector Information		30-pin, 2.54 mm spaced, dual-row header
Mating Connector	Details	Samtec: SSM-115-L-DV
	Included with Drive	No



P2 - Power Connector		
Connector Information		24-pin, 2.54 mm spaced, dual-row header
Mating Connector	Details	Samtec: BCS-112-L-D-PE
	Included with Drive	No



MOUNTING DIMENSIONS



PART NUMBERING INFORMATION

Example: D Z X R A L T E - 0 1 5 L 0 8 0

Drive Series	
DZ	DigiFlex Z (PCB Mount)

Drive Series	
X	Designed for Extended Environments

Communication	
R	RS232/RS485
C	CANopen or RS232

Command Inputs	
AN	Analog (±10V) No Step & Direction
AL	Analog (±10V) Low Voltage Step & Direction (5V)

Digital I/O	
T	TTL (5V) Non-Isolated

Motor Feedback	
E	Incremental Encoder and/or Halls

Max DC Bus Voltage (V_{DC})	
080	80

Power and Logic Supply	
L	DC Input Logic Supply Required

Peak Current ($A_{0\ to\ Peak}$)	
015	15

DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, *ADVANCED* Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- Optimized Footprint
- Private Label Software
- OEM Specified Connectors
- No Outer Case
- Increased Current Resolution
- Increased Temperature Range
- Custom Control Interface
- Integrated System I/O
- Tailored Project File
- Silkscreen Branding
- Optimized Base Plate
- Increased Current Limits
- Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- Reduced Profile Size and Weight

Feel free to contact Applications Engineering for further information and details.

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

Power Supplies

Shunt Regulators

Mounting Card MC1XDZR02

Drive(s)

Filter Cards

To Motor

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.