

DIGIFLEX® DIGITAL SERVO DRIVES MODEL: DR101EE20A8BDC-QD1

FEATURES:

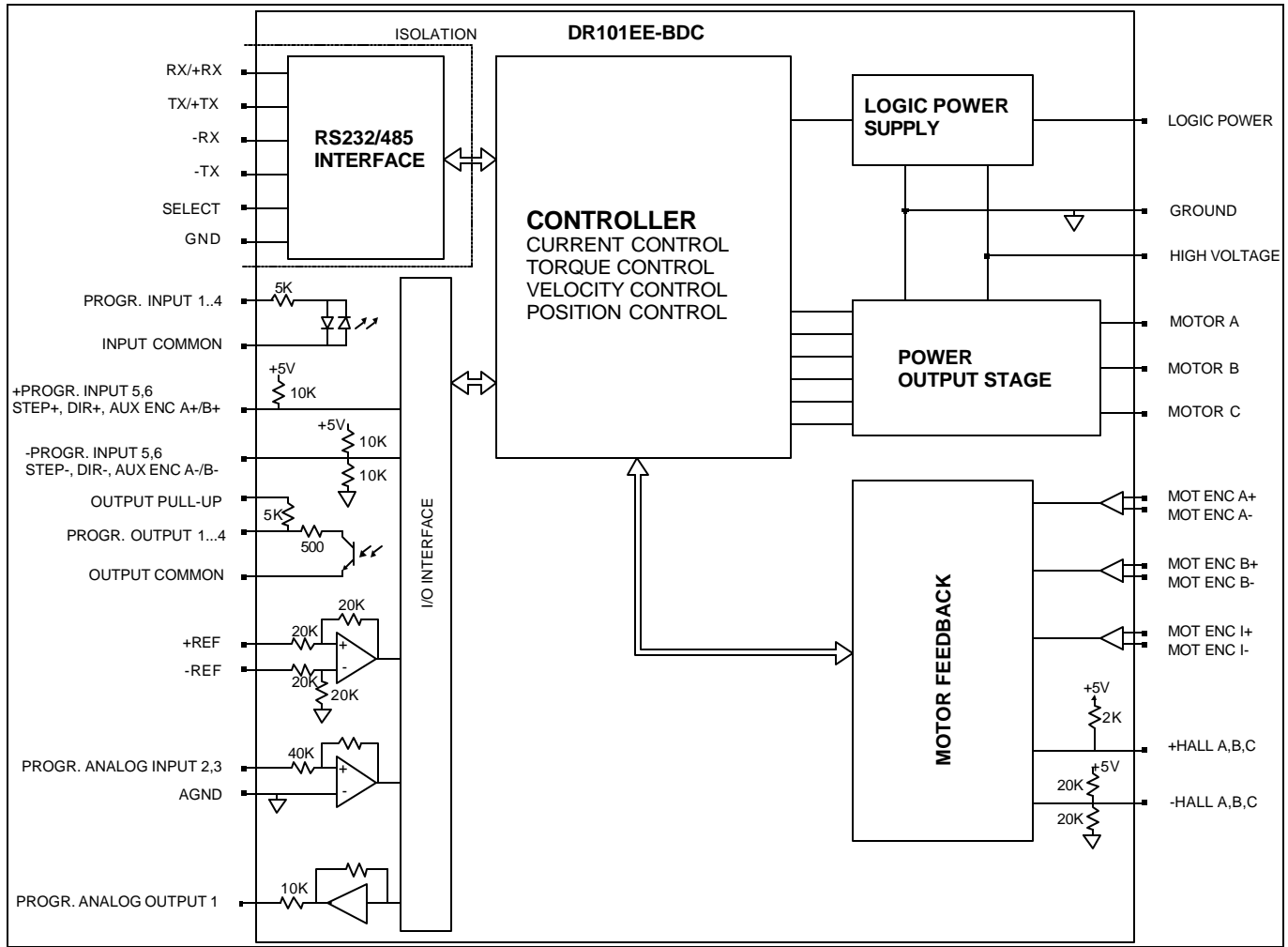
- Fully digital, state-of-the-art design
 - Space Vector Modulation and vector control technology
 - 20kHz Digital current loop with programmable gain settings
 - PIDF velocity loop with 100microsecond update rate
 - PID + FF position loop with 100 microsecond update rate
 - Hall sensor + encoder or encoder-only based commutation
 - Surface-mount technology
 - Small size, low cost, ease of use
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- Isolated RS232/485 interface for setup and networking
 - Windows© based setup software with built-in 8-channel digital scope
 - Operates in torque, velocity or position mode with programmable gain settings
 - Programmable profiling in all modes
 - Fully configurable current, voltage, velocity and position limits.
 - Step & direction mode for stepper replacement
 - Encoder following with programmable gear ratio
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- 4 isolated programmable digital inputs
 - 2 programmable differential inputs, configurable as step & direction, master encoder, or secondary encoder for dual loop operation
 - 4 isolated programmable digital outputs
 - 2 programmable analog inputs (10-bit)
 - 14-bit reference input or programmable analog input
 - 1 programmable analog output (10-bit)
 - Encoder output (from motor, optionally buffered)
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- Four quadrant regenerative operation
 - Separate backup logic supply input
 - Bi-color LED status indicator
 - Extensive built-in protection against:
 - over-voltage (programmable)
 - under-voltage (programmable)
 - short-circuit: phase-phase, phase-ground
 - over-current
 - over-temperature



ADVANCED MOTION CONTROLS

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BLOCK DIAGRAM:



DESCRIPTION:

The DR101EE Series digital PWM servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

DR101EE Series drives feature a single, isolated RS232/485 interface, which is used for drive configuration and setup as well as online operation in networked applications. Drive commissioning can be accomplished through a fully graphical Windows© based application.

All drive and motor parameters are stored in non-volatile memory.

SPECIFICATIONS:

POWER STAGE SPECIFICATIONS	DR101EE20A8BDC-QD1
DC SUPPLY VOLTAGE	20...80 VDC
PEAK CURRENT	20A (14.2Arms)
MAXIMUM CONTINUOUS CURRENT	10A (7.1Arms)
MINIMUM LOAD INDUCTANCE	250 μ H
SWITCHING FREQUENCY	20 kHz
HEATSINK (BASEPLATE) TEMPERATURE RANGE	0 to 65 °C, disables at 65 °C
POWER DISSIPATION AT CONTINUOUS CURRENT	50W
MIN. UNDER VOLTAGE SHUTDOWN	20 VDC
MAX. OVER-VOLTAGE SHUTDOWN	86 VDC
LOGIC SUPPLY VOLTAGE (backup supply)	20...80 VDC, 20W maximum

MECHANICAL SPECIFICATIONS	
LOGIC BACKUP CONNECTOR: P1	2-pin; 5.08mm pitch removable with screw flange
POWER CONNECTOR: P2	2-pin; 7.62mm pitch removable with screw flange
MOTOR CONNECTOR: P3	3-pin; 7.62mm pitch removable with screw flange
MOTOR FEEDBACK CONNECTOR: CN3*	15-pin high density female D-sub
I/O CONNECTOR: CN2*	26-pin high density female D-sub
COMMUNICATIONS INTERFACE (RS232/485): CN1*	9-pin female D-sub
SIZE	5.22 x 3.52 x 1.42 inches 132.5 x 89.5 x 35.9 mm
WEIGHT	1 lb. 0.44 kg

* Mating connectors are not included.

PIN FUNCTIONS:

P1 – Logic Backup Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
P1	1	GND	Ground	GND
	2	LOGIC PWR	Logic supply input. This input can be used to supply power to the drive logic circuitry only. Effective only when the voltage applied to pin P2-2 is lower than the voltage applied to P1-2.	I

P2 – Power Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
P2	1	GND	Ground	GND
	2	HV IN	DC power input. This input is used to supply power to the motor and drive logic circuitry.	I

P3 - Motor Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
P3	1	MA	Motor phase A	O
	2	MB	Motor phase B	O
	3	MC	Motor phase C	O

CN3 - Motor Feedback Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
CN3	1	+Hall A	Commutation sensor inputs. Internal 2K pull-up to +5VDC. Can be used with single ended or differential Hall sensors.	I
	2	+Hall B		I
	3	+Hall C		I
	4	MOT ENC A+	Differential Encoder Input. For single ended encoder signals, leave the A-terminal open.	I
	5	MOT ENC A-		I
	6	MOT ENC B+	Differential Encoder Input. For single ended encoder signals, leave the B-terminal open.	I
	7	MOT ENC B-		I
	8	MOT ENC I+	Differential Encoder Input. For single ended encoder signals, leave the I-terminal open.	I
	9	MOT ENC I-		I
	10	-Hall A*	See CN3-1. Leave open in case of single ended Hall sensors.	I
	11	-Hall B*	See CN3-2. Leave open in case of single ended Hall sensors.	I
	12	SGND	Signal ground	SGND

	13	+5V OUT	+5V @ 250mA max. Short-circuit protected.	O
	14	PAI3	Programmable analog input, single ended, 10-bit	I
	15	-Hall C*	See CN3-3. Leave open in case of single ended Hall sensors.	I

CN2 – I/O Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
CN2	1	PDO1	Isolated programmable digital output, 24V @ 50mA max. Referenced to pin 8, Output Common.	O
	2	OUTPUT COMMON	Digital output common.	OGND
	3	PDO2	Isolated programmable digital output, 24V @ 50mA max. Referenced to pin 8, Output Common.	O
	4	+REF	Differential reference signal input, 14-bit resolution. Can also be used as programmable analog input 1.	I
	5	-REF		I
	6	PAI2	Programmable analog input	I
	7	PAO1	Programmable analog output	O
	8	OUTPUT PULL-UP	Digital output pull-up via 5K resistor.	I
	9	-PDI6	Programmable Input (see CN2-18) or Direction- or Aux Enc B-	I
	10	PDO3	Isolated programmable digital output, 24V @ 50mA max. Referenced to pin 8, Output Common.	O
	11	PDI1	Isolated programmable digital input, 24V @ 5mA max. Referenced to pin 15, Input Common.	I
	12	PDI2	Isolated programmable digital input, 24V @ 5mA max. Referenced to pin 15, Input Common.	I
	13	PDI3	Isolated programmable digital input, 24V @ 5mA max. Referenced to pin 15, Input Common.	I
	14	PDO4	Isolated programmable digital output, 24V @ 50mA max. Referenced to pin 8, Output Common.	O
	15	Input Common	Digital input common. Can also be used to pull-up digital inputs.	IGND
	16	AGND	Analog ground	AGND
	17	+PDI5	Programmable differential digital input, or Step+ or Aux Enc A+	I
	18	+PDI6	Programmable, differential digital input or Direction+ or Aux Enc B+	I
	19	PDI4	Isolated programmable digital input, 24V @ 5mA max. Referenced to pin 15, Input Common.	I
	20	Encoder Channel A+	Encoder Output (from connector CN3),	O

	21	Encoder Channel A-	not buffered	O
	22	Encoder Channel B+	Encoder Output (from connector CN3), not buffered	O
	23	Encoder Channel B-		O
	24	Encoder Channel I+	Encoder Output (from connector CN3), not buffered	O
	25	Encoder Channel I-		O
	26	-PDI5	Programmable Input (See CN2-17) or Step- or Aux Enc A-	I

CN1 - Communications Interface (RS232/485):

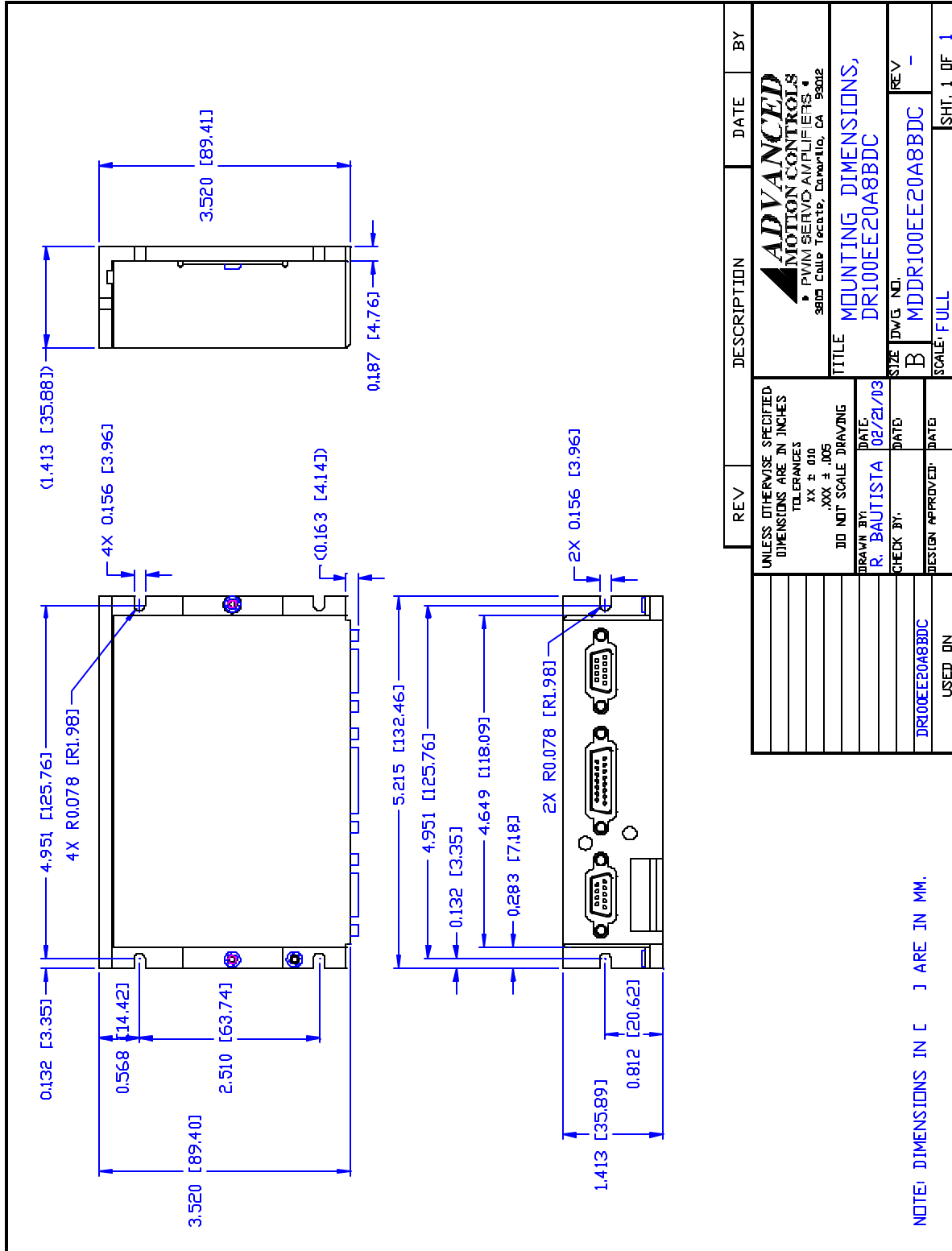
CONNECTOR	PIN	NAME	DESCRIPTION	I/O
CN1	1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
	2	TX/+TX	RS232: Transmit; RS485: +TX	O
	3	RX/+RX	RS232: Receive; RS 485: +RX	I
	4	N/C	Not connected	
	5	SGND	Signal ground	SGND
	6	-TX	RS485: -TX	O
	7	N/C	Not connected	
	8	-RX	RS485: -RX	I
	9	N/C	Not connected	

ORDERING INFORMATION:

Standard model: DR101EE20A8BDCX-QD1

X indicates the current revision letter.

MOUNTING DIMENSIONS:



REV	DESCRIPTION	DATE	BY
	ADVANCED MOTION CONTROLS PWIN SERVO AMPLIFIERS 3810 Calle Techaro, Campbell, CA 95002		
	TITLE: MOUNTING DIMENSIONS, DR100EE20A8BDC		
	SIZE: DWG NO. B	REV: -	
	SCALE: FULL	SHT. 1 OF 1	
	UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES		
	TOLERANCES: XX ± .010, .XXX ± .005		
	DO NOT SCALE DRAWING		
	DRAWN BY: R. BAUTISTA, DATE: 02/21/13		
	CHECK BY: , DATE:		
	DESIGN APPROVED: , DATE:		
	USED ON: DR100EE20A8BDC		