

**Description**

The DigiFlex Performance (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a single RS232/RS485 interface used for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at [www.a-m-c.com](http://www.a-m-c.com).

All drive and motor parameters are stored in non-volatile memory.

**Power Range**

Peak Current	60 A (42.4 A <sub>RMS</sub> )
Continuous Current	30 A (21.2 A <sub>RMS</sub> )
Supply Voltage	155 - 480 VAC



**Features**

- ▲ Four quadrant regenerative operation
- ▲ Space vector modulation (SVM) technology
- ▲ Fully digital state-of-the-art design
- ▲ Programmable gain settings
- ▲ Fully configurable current, voltage, velocity and position limits
- ▲ PIDF velocity loop
- ▲ PID + FF position loop
- ▲ Compact size, high power density

**MODES OF OPERATION**

- Current
- Position
- Velocity

**COMMAND SOURCE**

- ±10 V Analog
- 5V Step & Direction
- Encoder Following

**FEEDBACK SUPPORTED**

- Resolver
- ±10 V Analog
- Auxiliary Incremental Encoder

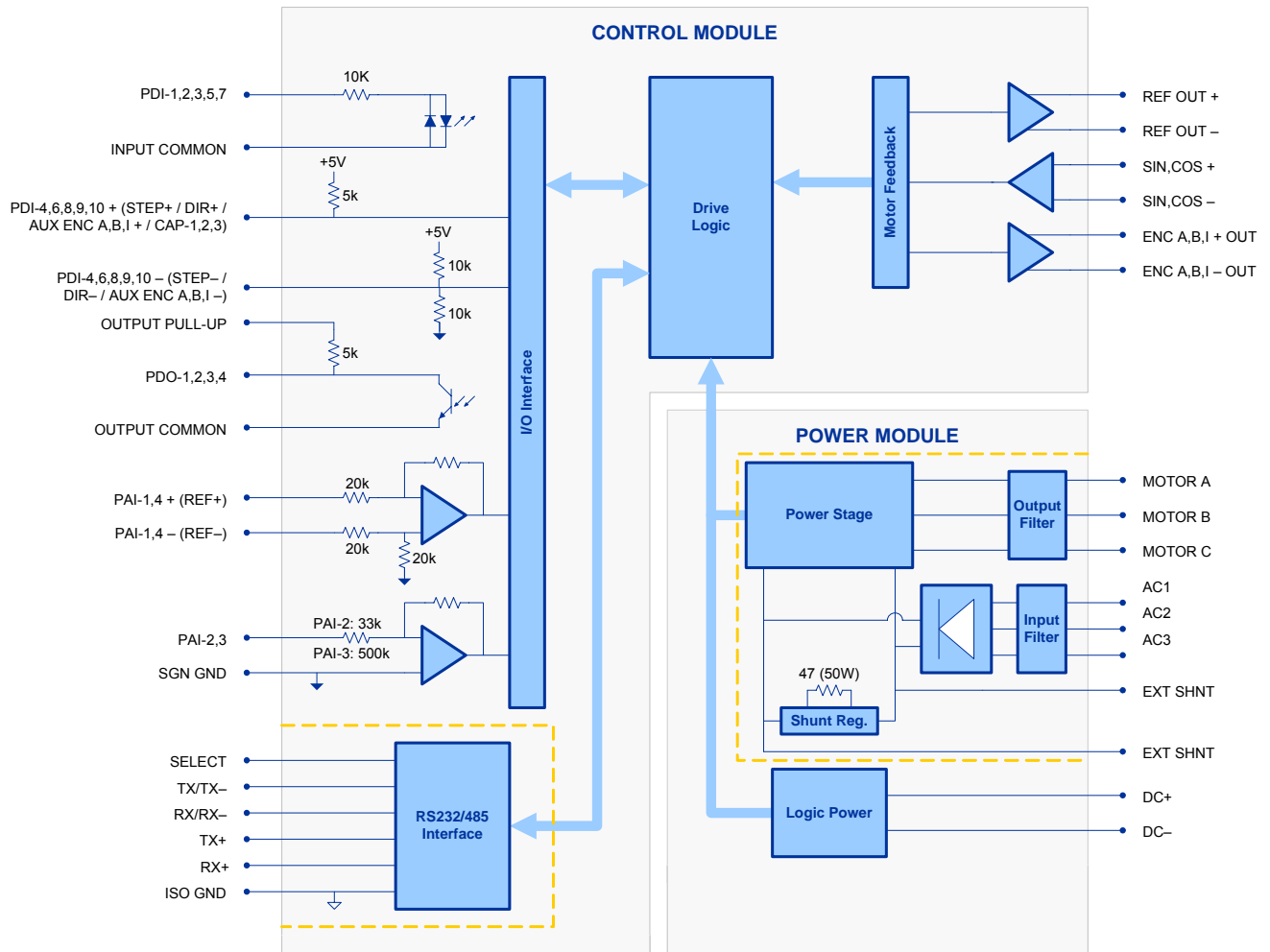
**INPUTS/OUTPUTS**

- 3 Programmable Analog Inputs
- 0 Programmable Analog Outputs
- 5 Programmable Digital Inputs (Differential)
- 5 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs




**COMPLIANCES & AGENCY APPROVALS**

- RoHS
- UL/cUL Pending
- CE Pending

**BLOCK DIAGRAM**



**Approvals and Compliances**

	<p>US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.</p>
	<p>Compliant with European CE for both the Class A EMC Directive 89/336/EEC on Electromagnetic Compatibility (specifically EN 61000-6-4:2001, EN 61000-6-2:2001, EN 61000-3-2:2000, and EN 61000-3-3:1995/A1:2001) and LVD requirements of directive 73/23/EEC (specifically EN 60204-1), a low voltage directive to protect users from electrical shock.</p>
	<p>RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.</p>

**SPECIFICATIONS**

Power Stage Specifications		
Description	Units	Value
AC Supply Voltage	VAC	155 - 480
DC Supply Voltage	VDC	220 - 800
Over Voltage Limit	VDC	850
Under Voltage Limit	VDC	215
Logic Supply Voltage	VDC	20 - 30
Peak Output Current	A	60
Maximum Continuous Output Current	A	30
Maximum Continuous Output Power	W	24000
Maximum Power Dissipation at Continuous Current	W	1200
Internal Shunt Resistor	-	Yes
Minimum Load Inductance (Line-To-Line) <sup>1</sup>	μH	3000
Switching Frequency	kHz	10
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
Control Specifications		
Description	Units	Value
Communication Interfaces	-	RS-232, RS-485
Command Sources	-	±10 V Analog, 5V Step & Direction, Encoder Following
Feedback Supported	-	±10 V Analog, Auxiliary Incremental Encoder, Resolver
Commutation Methods	-	Sinusoidal
Modes of Operation	-	Current, Position, Velocity
Motors Supported	-	Brushed, Brushless, Induction, Voice Coil
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	3/0
Current Loop Sample Time	μs	100
Velocity Loop Sample Time	μs	100
Position Loop Sample Time	μs	100
Resolver Reference/Excitation Signal	Vrms	4 Vrms @ 5 kHz
Expected Resolver Transformation Ratio	Vrms	0.5
Mechanical Specifications		
Description	Units	Value
Size (H x W x L)	mm (in)	330 x 256 x 63 (13 x 10.1 x 2.5)
Heatsink (Base) Temperature Range <sup>2</sup>	°C (°F)	0 - 65 (32 - 149)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Cooling System	-	Natural Convection
Form Factor	-	Stand Alone
IP Rating	-	IP10
CN1 - RS232/RS485 Communication Connector	-	9-pin, female D-sub
CN2 - Signal Connector	-	26-pin, high-density, female D-sub
CN3 - Feedback Connector	-	15-pin, high-density, female D-sub
CN4 - Auxiliary Feedback Connector	-	15-pin, high-density, male D-sub
P1 - Logic Power Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
P2 - Power Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
P3 - Power Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
P4 - Power Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header

**Notes**

1. Low inductance motors, such as 'pancake' and 'basket-wound', require external inductors. The Minimum Load Inductance provided assumes the highest allowed bus voltage. Lower inductances are acceptable for lower bus voltages.
2. Additional cooling and/or heatsink may be required to achieve rated performance.

**PIN FUNCTIONS**

CN1 - RS232/RS485 Communication Connector			
Pin	Name	Description / Notes	I/O
1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
2	RS232 TX / RS485 TX-	Transmit Line (RS-232 or RS-485)	O
3	RS232 RX / RS485 RX-	Receive Line (RS-232 or RS-485)	I
4	RESERVED	Reserved	-
5	ISO GND	Isolated Signal Ground	IGND
6	RS485 TX+	Transmit Line (RS-485)	O
7	RESERVED	Reserved	-
8	RS485 RX+	Receive Line (RS-485)	I
9	RESERVED	Reserved	-

CN2 - Signal Connector			
Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PDI-4 - (STEP-)	Programmable Digital Input or Step- (For Differential Signals Only)	I
5	PDI-6 - (DIR-)	Programmable Digital Input or Direction- (For Differential Signals Only)	I
6	PAI-1	Programmable Analog Input	I
7	SGN GND	Signal Ground	SGND
8	OUTPUT PULL-UP	Digital Output Pull-Up	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4 + (STEP+)	Programmable Digital Input or Step+	I
18	PDI-6 + (DIR+)	Programmable Digital Input or Direction+	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	Emulated Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Emulated Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Emulated Encoder Index Output	O
25	ENC I- OUT		O
26	SGN GND	Signal Ground	SGND

CN3 - Feedback Connector			
Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

CN4 - Auxiliary Feedback Connector			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (AUX ENC A+ / CAP-2)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture	I
5	PDI-8 - (AUX ENC A-)	Programmable Digital Input or Auxiliary Encoder (For Differential Signals Only)	I
6	PDI-9 + (AUX ENC B+ / CAP-2)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture	I
7	PDI-9 - (AUX ENC B-)	Programmable Digital Input or Auxiliary Encoder (For Differential Signals Only)	I
8	PDI-10 + (AUX ENC I+ / CAP-1)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture	I
9	PDI-10 - (AUX ENC I-)	Programmable Digital Input or Auxiliary Encoder (For Differential Signals Only)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input	I
15	PAI-4 -		I

P1 - Logic Power Connector			
Pin	Name	Description / Notes	I/O
1	LOGIC PWR	Logic Supply Input	I
2	LOGIC GND	Logic Supply Ground	GND

P2 - Power Connector			
Pin	Name	Description / Notes	I/O
1	PE	Protective Earth Ground	PE
2	MOTOR C	Motor Phase C	O
3	MOTOR B	Motor Phase B	O
4	MOTOR A	Motor Phase A	O

P3 - Power Connector			
Pin	Name	Description / Notes	I/O
1	PE	Protective Earth Ground	PE
2	AC3	AC Supply Input (Single Or Three Phase)	I
3	AC2		I
4	AC1		I

**P4 - Power Connector**

Pin	Name	Description / Notes	I/O
1	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	O
2	DC-		O
3	DC+		O
4	DC+		O

**HARDWARE SETTINGS**

**Switch Functions**

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary value of drive address/ID.	1	0
2	Bit 1 of binary value of drive address/ID.	1	0
3	Bit 2 of binary value of drive address/ID.	1	0
4	Bit 3 of binary value of drive address/ID.	1	0
5	Bit 4 of binary value of drive address/ID.	1	0
6	Bit 5 of binary value of drive address/ID.	1	0
7	Bit 0 of binary value of drive bit rate setting.	1	0
8	Bit 1 of binary value of drive bit rate setting.	1	0

*Additional Details*

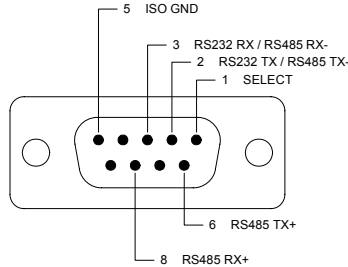
The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Bit Rate (kbits/sec)		Value For Bit Rate Setting
CANopen	RS-485	
Load from non-volatile memory	Load from non-volatile memory	0
500	9.6	1
250	38.4	2
125	115.2	3

**MECHANICAL INFORMATION**

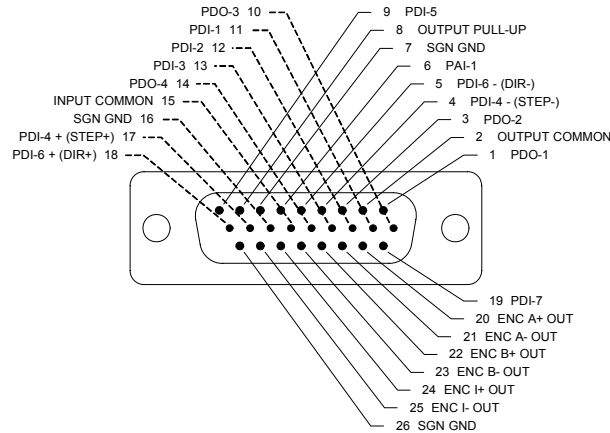
**CN1 - RS232/RS485 Communication Connector**

Connector Information	9-pin, female D-sub
Mating Connector	AMP: Plug P/N 205204-4; Housing P/N 748677-1; Terminals P/N 5-66507-7 (loose) or 3-66507-0 (strip)



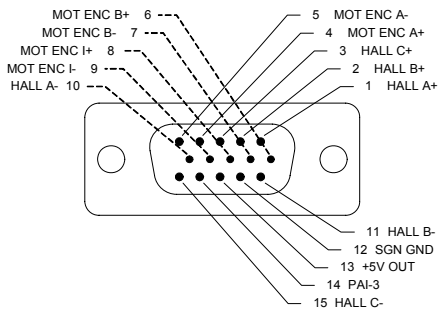
**CN2 - Signal Connector**

Connector Information	26-pin, high-density, female D-sub
Mating Connector	AMP: Plug P/N 748365-1; Housing P/N 748677-2; Terminals P/N 748333-4 (loose) or 748333-2 (strip)



**CN3 - Feedback Connector**

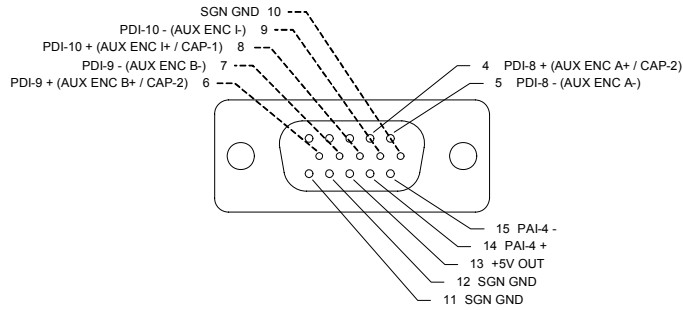
Connector Information	15-pin, high-density, female D-sub
Mating Connector	AMP: Plug P/N 748365-1; Housing P/N 748677-1; Terminals P/N 748333-4 (loose) or 748333-2 (strip)





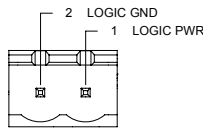
**CN4 - Auxiliary Feedback Connector**

Connector Information	15-pin, high-density, male D-sub
Mating Connector	AMP: Plug P/N 748365-1; Housing P/N 748677-1; Terminals P/N 748610-4 (loose) or 748610-2 (strip)



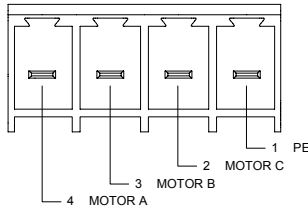
**P1 - Logic Power Connector**

Connector Information	2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1757019



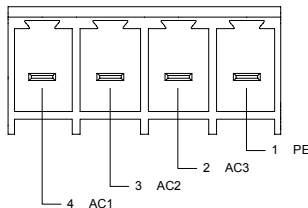
**P2 - Power Connector**

Connector Information	4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1804920



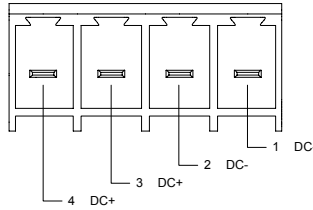
**P3 - Power Connector**

Connector Information	4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1804920



**P4 - Power Connector**

Connector Information	4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1804920



**PART NUMBERING INFORMATION**

Ex: **D P R A N I E - 0 8 0 A 0 1 5**

Drive Series	
DP	DigiFlex Performance

Communication	
R	RS232/RS485
C	CANopen or RS232
Q	SynqNet

Command Inputs	
AN	Analog (±10V) No Step & Direction
AL	Analog (±10V) Low Voltage Step & Direction (5V)
AH	Analog (±10V) High Voltage Step & Direction (24V)
NL	No Analog Low Voltage Step & Direction (5V)
NN	No Analog, No Step & Direction (Communication Interface Only)

Digital I/O	
I	Isolated (24V)
T	TTL (5V) Non-Isolated

Motor Feedback	
E	Incremental Encoder and/or Halls
R	Resolver
A	Absolute Sin/Cos (Hiperface & Endat)
S	Sin/Cos with Halls

Max DC Bus Voltage (V <sub>DC</sub> )	
080	80
200	200
400	400
800	800

Power and Logic Supply	
A	AC Input +24V <sub>DC</sub> User Logic Supply Required
N	AC Input Only No Logic Supply Required (Internal Supply)
B	DC Input Both Logic Supply Options (Internal or User)
L	DC Input Logic Supply Required
D	DC Input Only Internal Logic Supply

Peak Current (A <sub>0 to Peak</sub> )	
015	15
016	16
020	20
025	25
030	30
040	40
060	60
100	100

**Disclaimer**

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.