Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a SynqNet™ interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Range

Peak Current	60 A (42.4 A_{RMS})
Continuous Current	30 A (21.2 A_{RMS})
Supply Voltage	200 - 480 VAC

Features

- Four Quadrant Regenerative Operation
- Space Vector Modulation (SVM) Technology
- Fully Digital State-of-the-art Design
- Programmable Gain Settings
- Compact Size, High Power Density
- 16-bit Analog to Digital Hardware
- Built-in brake/shunt regulator

MODES OF OPERATION
- Current

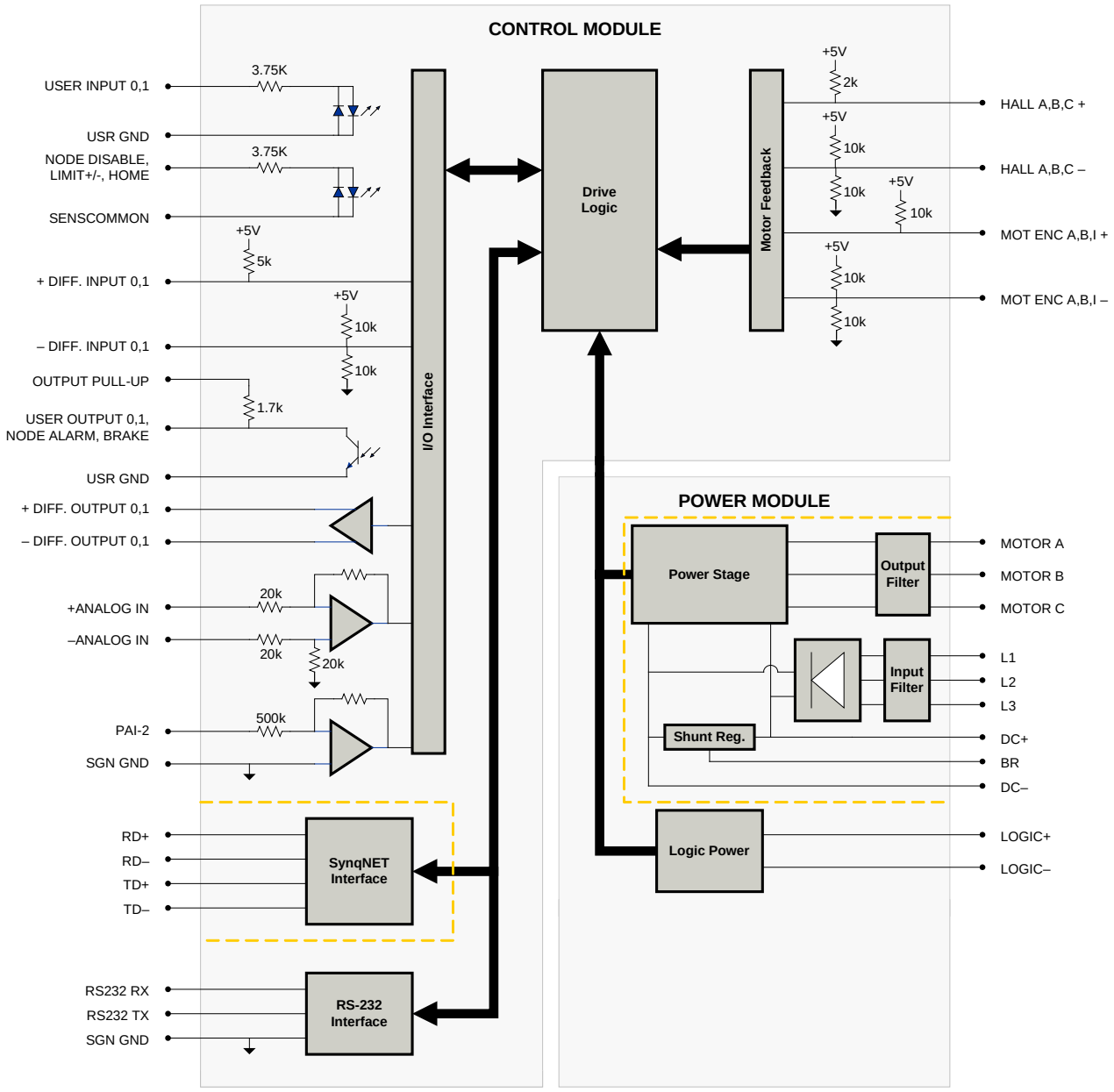
COMMAND SOURCE
- Over the Network

FEEDBACK SUPPORTED
- Halls
- Incremental Encoder

INPUTS/OUTPUTS
- 3 Dedicated Digital Inputs
- 2 Dedicated Digital Outputs
- 2 High Speed Captures
- 2 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 2 Programmable Digital Inputs (Differential)
- 2 Programmable Digital Inputs (Single-Ended)
- 2 Programmable Digital Outputs (Differential)
- 2 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

BLOCK DIAGRAM



Information on Approvals and Compliances	
CE	Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.
RoHS COMPLIANCE	RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

SPECIFICATIONS

Power Specifications		
Description	Units	Value
Rated Voltage	VAC (VDC)	480 (678)
AC Supply Voltage Range	VAC	200 - 480
AC Supply Minimum	VAC	180
AC Supply Maximum	VAC	528
AC Input Phases	-	3
AC Supply Frequency	Hz	50 - 60
DC Supply Voltage Range[1]	VDC	255 - 747
DC Bus Over Voltage Limit	VDC	850
DC Bus Under Voltage Limit	VDC	230
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)
Maximum Peak Output Current[2]	A (Arms)	60 (42.4)
Maximum Continuous Output Current	A (Arms)	30 (21.2)
Max. Continuous Output Power @ Rated Voltage[3]	W	13680
Max. Continuous Power Dissipation @ Rated Voltage	W	720
Internal Bus Capacitance	µF	330
External Shunt Resistor Minimum Resistance[4]	Ω	40
Minimum Load Inductance (Line-To-Line)[5]	µH	3000
Switching Frequency	kHz	8
Maximum Output PWM Duty Cycle	%	100
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
Control Specifications		
Description	Units	Value
Communication Interfaces	-	SynqNet (RS-232 for configuration)
Command Sources	-	Over the Network
Feedback Supported	-	Halls, Incremental Encoder
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	4/2
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	2/0
Current Loop Sample Time	µs	125
Maximum Encoder Frequency	MHz	5 (1.25 pre-quadrature)
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	No
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), RoHS
Size (H x W x D)	mm (in)	300.5 x 232.1 x 139.3 (11.8 x 9.1 x 5.5)
Weight	g (oz)	6174 (217.8)
Heatsink (Base) Temperature Range[6]	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
Cooling System	-	Natural Convection
IP Rating	-	IP10
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header
COMM IN Connector	-	Shielded RJ-45 socket with LEDs
COMM OUT Connector	-	Shielded RJ-45 socket with LEDs
DC BUS Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
MOTOR POWER Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
POWER Connector	-	3-port, 7.62 mm spaced, enclosed, friction lock header

Notes

1. DC supply operation through the L1, L2, or L3 terminals will reduce peak/cont. current ratings by 30%. See installation manual for details.
2. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
3. P = (DC Rated Voltage) * (Cont. RMS Current) * 0.95.
4. *ADVANCED* Motion Controls recommends using an external fuse in series with the shunt resistor. A 3 amp motor delay fuse is typical.
5. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
6. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

+24V LOGIC - Logic Power Connector

Pin	Name	Description / Notes	I/O
1	LOGIC PWR	Logic Supply Input	I
2	LOGIC GND	Logic Supply Ground	GND

AUX COMM - RS232 Communication Connector

Pin	Name	Description / Notes	I/O
1	RS232 RX	Receive Line (RS-232)	I
2	RS232 TX	Transmit Line (RS-232)	O
3	SGN GND	Signal Ground	SGND

COMM IN - SynqNet Communication Connector

Pin	Name	Description / Notes	I/O
1	RD+	Receiver Line (100BaseT)	I
2	RD-		I
3	TD+	Transmitter Line (100BaseT)	O
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	TD-	Transmitter Line (100BaseT)	O
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

COMM OUT - SynqNet Communication Connector

Pin	Name	Description / Notes	I/O
1	TD+	Transmitter Line (100BaseT)	O
2	TD-		O
3	RD+	Receiver Line (100BaseT)	I
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RD-	Receiver Line (100BaseT)	I
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

DC BUS - Power Connector

Pin	Name	Description / Notes	I/O
1	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	O
2	BR	External Brake Resistor Connection	-
3	DC+	Brake Resistor DC+. Connection for brake resistor.	O
4	DC+	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	O

FEEDBACK - Feedback Connector

Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-2	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

I/O - Signal Connector			
Pin	Name	Description / Notes	I/O
1	USER OUTPUT 0 (PDO-1)	24V Isolated Programmable Digital Output (Referenced To USER GND)	O
2	USER OUTPUT 1 (PDO-2)	24V Isolated Programmable Digital Output (Referenced To USER GND)	O
3	USER GND	Ground Reference For User Outputs And Inputs	ISOGND
4	NODE ALARM (PDO-12)	24V Network Error (Isolated Output Referenced To USER GND)	O
5	BRAKE (PDO-13)	24V Brake (Isolated Output Referenced to USER GND)	O
6	SGN GND	Signal Ground	SGND
7	+ DIFF. INPUT 0 (PDI-3)	5V Non-Isolated Differential Digital Input	I
8	- DIFF. INPUT 0 (PDI-3)		I
9	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
10	NODE DISABLE (PDI-12)	24V Node Disable (Isolated Input Referenced to SENSCOMMON)	I
11	LIMIT + (PDI-9)	24V Positive Limit (Isolated Input Referenced To SENSCOMMON)	I
12	LIMIT - (PDI-10)	24V Negative Limit (Isolated Input Referenced To SENSCOMMON)	I
13	HOME (PDI-11)	24V Home Switch (Isolated Input Referenced To SENSCOMMON)	I
14	USER INPUT 0 (PDI-1)	24V Isolated Programmable Digital Input (Referenced To USER GND)	I
15	USER INPUT 1 (PDI-2)	24V Isolated Programmable Digital Input (Referenced To USER GND)	I
16	SENSCOMMON	Sensor Common (Can Be Used To Pull-Up Related Inputs)	CMN
17	+ DIFF. INPUT 1 (PDI-4)	5V Non-Isolated Differential Digital Input	I
18	- DIFF. INPUT 1 (PDI-4)		I
19	SGN GND	Signal Ground	SGND
20	+ DIFF. OUTPUT 0 (PDO-3)	5V Non-Isolated Differential Digital Output	O
21	- DIFF. OUTPUT 0 (PDO-3)		O
22	+ DIFF. OUTPUT 1 (PDO-4)	5V Non-Isolated Differential Digital Output	O
23	- DIFF. OUTPUT 1 (PDO-4)		O
24	+ ANALOG IN (PAI-1)	±10V Programmable Differential Analog Input (16-bit Resolution)	I
25	- ANALOG IN (PAI-1)		I
26	SGN GND	Signal Ground	SGND

MOTOR POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	SHIELD	Motor feedback cable shield. Internally connected to protective earth ground.	-
2	MOTOR C	Motor Phase C	O
3	MOTOR B	Motor Phase B	O
4	MOTOR A	Motor Phase A	O

POWER - Power Connector			
Pin	Name	Description / Notes	I/O
1	L3	AC Supply Input (Three Phase)	I
2	L2		I
3	L1		I

HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
7	Bit 6 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
8	Bit 7 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0

LED Functions

LINK_IN LED	
On	Receive Valid
Off	Not Valid or Power Off or Reset

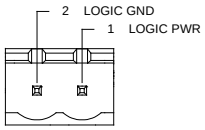
CYCLIC LED	
On	Network Cyclic
Off	Power Off or Reset
Blinking	Network Not Cyclic

LINK_OUT LED	
On	Receive Valid
Off	Not Valid or Power Off or Reset

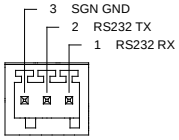
REPEATER LED	
On	Repeater On, Network Cyclic
Off	Repeater Off or Power Off or Reset
Blinking	Repeater On, Network Not Cyclic

MECHANICAL INFORMATION

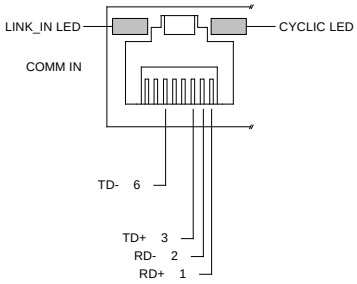
+24V LOGIC - Logic Power Connector		
Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1757019
	Included with Drive	Yes



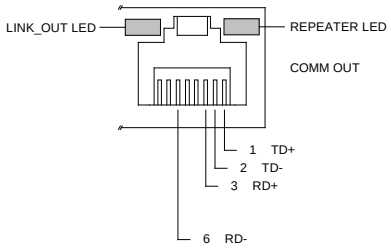
AUX COMM - RS232 Communication Connector		
Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
	Included with Drive	Yes



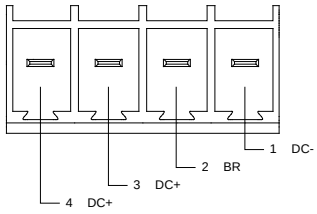
COMM IN - SynqNet Communication Connector		
Connector Information		Shielded RJ-45 socket with LEDs
Mating Connector	Details	AMP: Plug P/N 5-569552-3
	Included with Drive	No



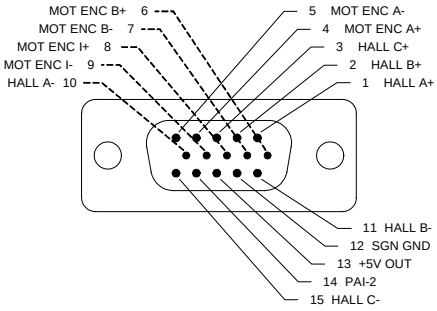
COMM OUT - SynqNet Communication Connector		
Connector Information		Shielded RJ-45 socket with LEDs
Mating Connector	Details	AMP: Plug P/N 5-569552-3
	Included with Drive	No



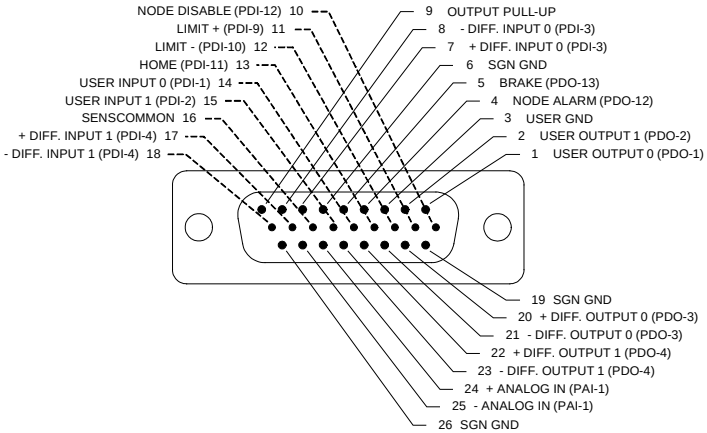
DC BUS - Power Connector		
Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
	Included with Drive	Yes



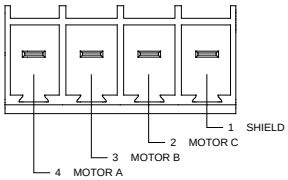
FEEDBACK - Feedback Connector		
Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



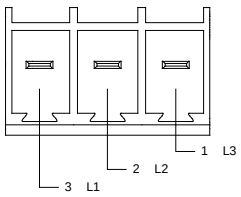
I/O - Signal Connector		
Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



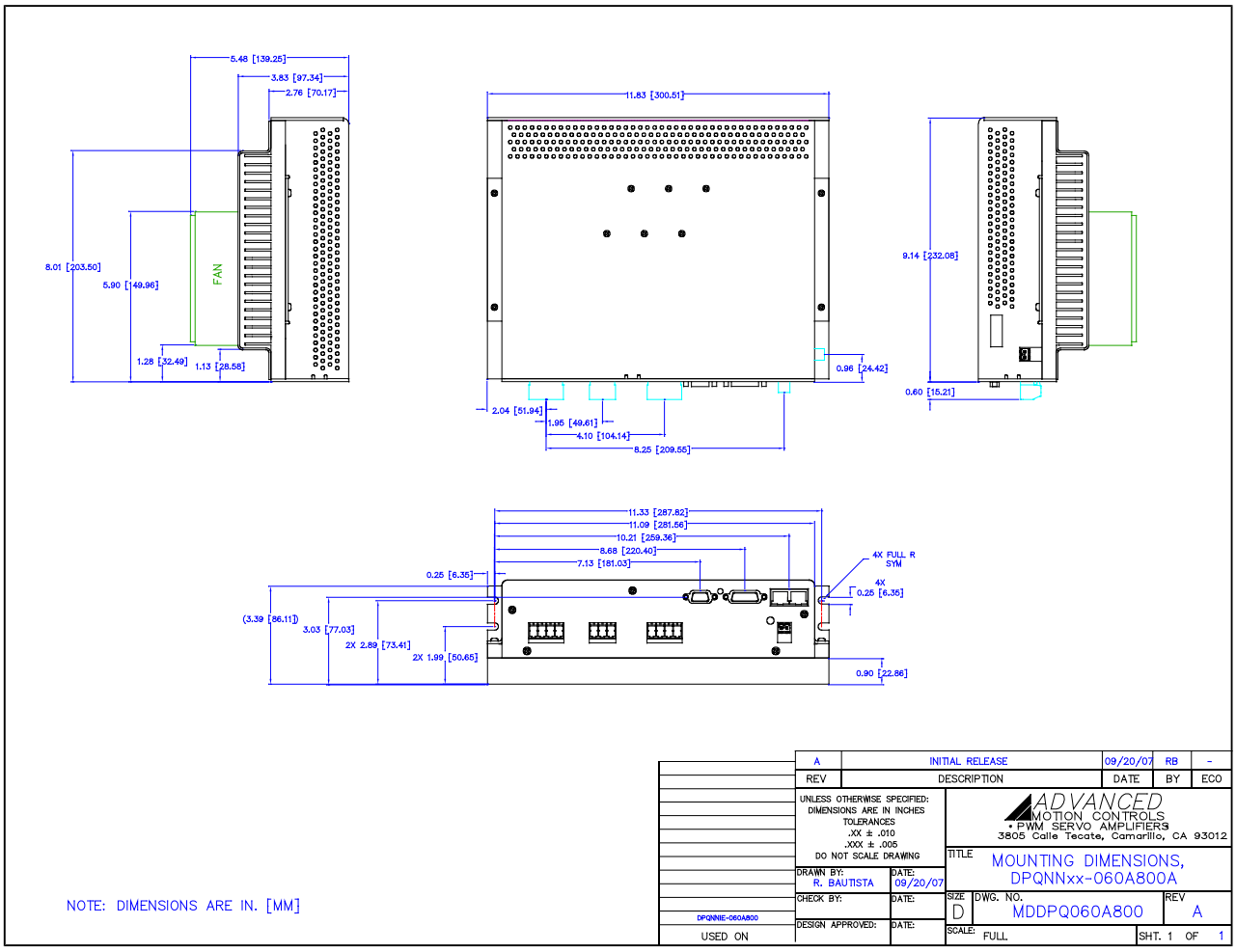
MOTOR POWER - Power Connector		
Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804920
	Included with Drive	Yes



POWER - Power Connector		
Connector Information		3-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix Contact: P/N 1804917
	Included with Drive	Yes



MOUNTING DIMENSIONS



PART NUMBERING INFORMATION

Example: D P R A N I E - 0 1 5 A 4 0 0 -

Drive Series	
DP	DigiFlex Performance

Communication	
R	RS232/RS485
C	CANopen or RS232
E	EtherCAT
Q	SynqNet

Command Inputs	
AN	Analog (±10V) No Step & Direction
AL	Analog (±10V) Low Voltage Step & Direction (5V)
AH	Analog (±10V) High Voltage Step & Direction (24V)
NL	No Analog Low Voltage Step & Direction (5V)
NN	No Analog, No Step & Direction (Communication Interface Only)

Digital I/O	
I	Isolated (24V)
T	TTL (5V) Non-Isolated

Motor Feedback	
E	Incremental Encoder and/or Halls
R	Resolver
A	Absolute Sin/Cos (Hiperface & Endat)
S	Sin/Cos with Halls
U	Universal (Halls, Inc. Enc., Abs. Enc., 1Vp-p Sin/Cos Enc.)

Customer Special
Code used to identify customer specials

Max DC Bus Voltage (V_{DC})	
080	80
200	200
400	400
800	800

Power and Logic Supply	
A	AC Input +24V_{DC} User Logic Supply Required
S	AC Input Single Phase Only +24V_{DC} User Logic Supply Required
B	DC Input Both Logic Supply Options (Internal or User)
L	DC Input Logic Supply Required

Peak Current ($A_{0\ to\ Peak}$)	
015	15
016	16
020	20
025	25
030	30
040	40
060	60
100	100

DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, *ADVANCED* Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- Optimized Footprint
- Private Label Software
- OEM Specified Connectors
- No Outer Case
- Increased Current Resolution
- Increased Temperature Range
- Custom Control Interface
- Integrated System I/O
- Tailored Project File
- Silkscreen Branding
- Optimized Base Plate
- Increased Current Limits
- Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

Drive(s)

Filter Cards

To Motor

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.