

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a SynqNet™ interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Range	
Peak Current	30 A (21.2 A _{RMS})
Continuous Current	15 A (10.6 A _{RMS})
Supply Voltage	100 - 240 VAC



Features

- ▲ Four Quadrant Regenerative Operation
- Space Vector Modulation (SVM) Technology
- ✓ Fully Digital State-of-the-art Design

- Compact Size, High Power Density
- 16-bit Analog to Digital Hardware
- Built-in brake/shunt regulator

MODES OF OPERATION

Current

COMMAND SOURCE

Over the Network

FEEDBACK SUPPORTED

- Halls
- Incremental Encoder

INPUTS/OUTPUTS

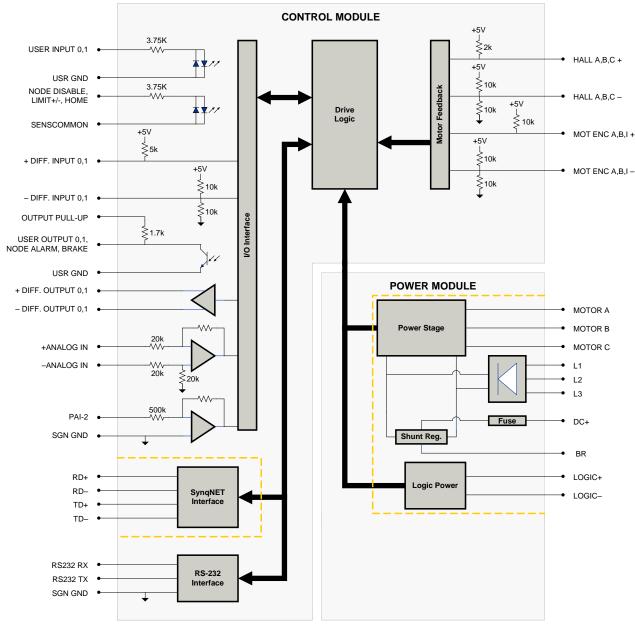
- 3 Dedicated Digital Inputs
- 2 Dedicated Digital Outputs
- 2 High Speed Captures
- 2 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 2 Programmable Digital Inputs (Differential)
- 2 Programmable Digital Inputs (Single-Ended)
- 2 Programmable Digital Outputs (Differential)
- 2 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS

- U
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS



BLOCK DIAGRAM



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products. Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock. ROHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.



SPECIFICATIONS

Description	Power S Units	Specifications Value
Rated Voltage	VAC (VDC)	240 (339)
AC Supply Voltage Range	VAC	100 - 240
AC Supply Minimum	VAC	90
AC Supply Maximum	VAC	264
AC Input Phases ¹	-	3
AC Supply Frequency	Hz	50 - 60
DC Supply Voltage Range ²	VDC	127 - 373
DC Bus Over Voltage Limit	VDC	429
DC Bus Under Voltage Limit	VDC	55
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA)
Maximum Peak Output Current ³	A (Arms)	30 (21.2)
Maximum Continuous Output Current	A (Arms)	15 (10.6)
Max. Continuous Output Power @ Rated Voltage4	W	3420
Max. Continuous Power Dissipation @ Rated Voltage	W	180
Internal Bus Capacitance	μF	1410
Minimum Load Inductance (Line-To-Line) ⁵	μH	600
Switching Frequency	kHz	16
Internal Shunt Fuse Rating	A	3 A time-delay fuse
Maximum Output PWM Duty Cycle	%	100
Low Voltage Supply Outputs	/6	+5 VDC (250 mA)
Description	Control : Units	Specifications Value
Communication Interfaces	- Offics	SynqNet (RS-232 for configuration)
Command Sources	-	Over the Network
Feedback Supported	-	Halls, Incremental Encoder
Commutation Methods	-	
Modes of Operation	-	Sinusoidal, Trapezoidal Current
·		
		40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)		4/2
Programmable Analog Inputs/Outputs (PAIs/PAOs)		2/0
Current Loop Sample Time	μs	62.5
Maximum Encoder Frequency	MHz	5 (1.25 pre-quadrature)
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	No
internal Shuff Resistor		
Description	Units	al Specifications Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL
Size (H x W x D)	mm (in)	202 x 157 x 70 (8 x 6.2 x 2.8)
Weight	g (oz)	1473 (52)
Heatsink (Base) Temperature Range ⁶	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
Cooling System	-	Natural Convection
IP Rating	-	IP10
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header with threaded flange
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header
COMM IN Connector	-	Shielded RJ-45 socket with LEDs
COMM OUT Connector	-	Shielded RJ-45 socket with LEDs
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
POWER Connector	-	8-contact, 11.10 mm spaced, dual-barrier terminal block
1 STATE OF CONTROLOR	-	o contact, 11.10 mm spaced, dual-partier terminal block

Notes

- Can operate on single-phase VAC if peak/cont. current ratings are reduced by at least 30%.

 DC Supply operation will reduce peak/cont. current ratings by at least 30%.

 Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.

 P = (DC Rated Voltage) * (Cont. RMS Current) * 0.95.

 Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.

 Additional cooling and/or heatsink may be required to achieve rated performance. 3.



PIN FUNCTIONS

		+24V LOGIC - Logic Power Connector	
Pin	Name	Description / Notes	1/0
1	LOGIC GND	Logic Supply Ground	GND
2	LOGIC PWR	Logic Supply Input	I

	AUX COMM - RS232 Communication Connector		
Pin	Name	Description / Notes	1/0
1	RS232 RX	Receive Line (RS-232)	I
2	RS232 TX	Transmit Line (RS-232)	0
3	SGN GND	Signal Ground	SGND

	COMM IN - SynqNet Communication Connector		
Pin	Name	Description / Notes	1/0
1	RD+	Descriper Line (400Descr)	I
2	RD-	Receiver Line (100BaseT)	I
3	TD+	Transmitter Line (100BaseT)	0
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	TD-	Transmitter Line (100BaseT)	0
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

	COMM OUT - SynqNet Communication Connector		
Pin	Name	Description / Notes	1/0
1	TD+	Transmitter Line (400DeceT)	0
2	TD-	Transmitter Line (100BaseT)	0
3	RD+	Receiver Line (100BaseT)	I
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RD-	Receiver Line (100BaseT)	I
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

		FEEDBACK - Feedback Connector	
Pin	Name	Description / Notes	1/0
1	HALL A+		I
2	HALL B+	Commutation Sensor Inputs	I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive	I
5	MOT ENC A-	Input)	I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive	I
7	MOT ENC B-	Input)	
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	
9	MOT ENC I-	Differential Encoder index input (For Single Ended Signals Ose Only The Positive Input)	I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	0
14	PAI-2	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	1



		I/O - Signal Connector	
Pin	Name	Description / Notes	1/0
1	USER OUTPUT 0 (PDO-1)	24V Isolated Programmable Digital Output (Referenced To USER GND)	0
2	USER OUTPUT 1 (PDO-2)	24V Isolated Programmable Digital Output (Referenced To USER GND)	0
3	USER GND	Ground Reference For User Outputs And Inputs	ISOGND
4	NODE ALARM (PDO-12)	24V Network Error (Isolated Output Referenced To USER GND)	0
5	BRAKE (PDO-13)	24V Brake (Isolated Output Referenced to USER GND)	0
6	SGN GND	Signal Ground	SGND
7	+ DIFF. INPUT 0 (PDI-3)	5) Also lasted Differential Digital Inner	I
8	- DIFF. INPUT 0 (PDI-3)	5V Non-Isolated Differential Digital Input	I
9	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
10	NODE DISABLE (PDI-12)	24V Node Disable (Isolated Input Referenced to SENSCOMMON)	I
11	LIMIT + (PDI-9)	24V Positive Limit (Isolated Input Referenced To SENSCOMMON)	I
12	LIMIT - (PDI-10)	24V Negative Limit (Isolated Input Referenced To SENSCOMMON)	
13	HOME (PDI-11)	24V Home Switch (Isolated Input Referenced To SENSCOMMON)	I
14	USER INPUT 0 (PDI-1)	24V Isolated Programmable Digital Input (Referenced To USER GND)	I
15	USER INPUT 1 (PDI-2)	24V Isolated Programmable Digital Input (Referenced To USER GND)	I
16	SENSCOMMON	Sensor Common (Can Be Used To Pull-Up Related Inputs)	CMN
17	+ DIFF. INPUT 1 (PDI-4)	CV New Joseph and Differential Digital Lauret	I
18	- DIFF. INPUT 1 (PDI-4)	5V Non-Isolated Differential Digital Input	I
19	SGN GND	Signal Ground	SGND
20	+ DIFF. OUTPUT 0 (PDO-3)	EVALUE Indicated Differential Digital Output	0
21	- DIFF. OUTPUT 0 (PDO-3)	5V Non-Isolated Differential Digital Output	0
22	+ DIFF. OUTPUT 1 (PDO-4)	EV Non located Differential Digital Output	0
23	- DIFF. OUTPUT 1 (PDO-4)	5V Non-Isolated Differential Digital Output	0
24	+ ANALOG IN (PAI-1)	40\/ Programmable Differential Angles Input (40 bit Decelution)	I
25	- ANALOG IN (PAI-1)	±10V Programmable Differential Analog Input (16-bit Resolution)	
26	SGN GND	Signal Ground	SGND

		POWER - Power Connector	
Pin	Name	Description / Notes	1/0
1	MOTOR A	Motor Phase A	0
2	MOTOR B	Motor Phase B	0
3	MOTOR C	Motor Phase C	0
4	DC+	Brake Resistor DC+. Connection for brake resistor.	0
5	BR	External Brake Resistor Connection	-
6	L1		I
7	L2	AC Supply Input (Single or Three Phase)	I
8	L3		I



HARDWARE SETTINGS

Switch Functions

Switch	Description	Sett	ing
Switch	Description	On	Off
1	Bit 0 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
7	Bit 6 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
8	Bit 7 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0

LED Functions

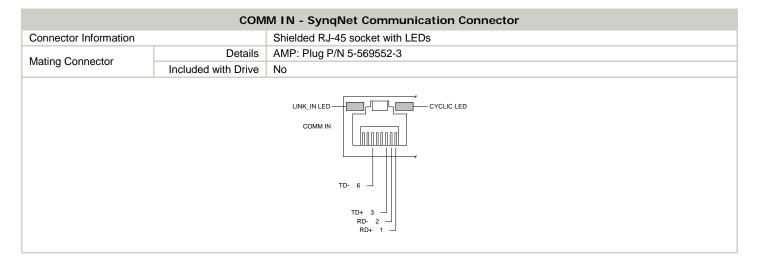
LED I MICHOID			
	LINK_IN LED		
On	Receive Valid		
Off	Not Valid or Power Off or Reset		
	CYCLIC LED		
On	Network Cyclic		
Off	Power Off or Reset		
Blinking	Network Not Cyclic		
LINK_OUT LED			
On	On Receive Valid		
Off	Not Valid or Power Off or Reset		
	REPEATER LED		
On	Repeater On, Network Cyclic		
Off	Repeater Off or Power Off or Reset		
Blinking	Repeater On, Network Not Cyclic		



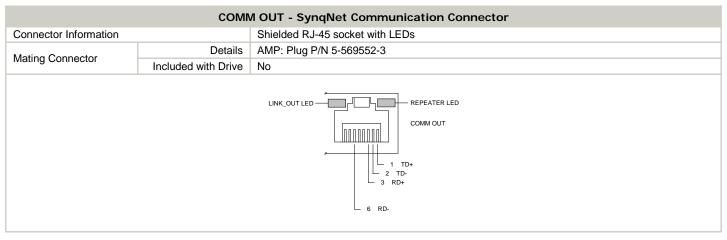
MECHANICAL INFORMATION

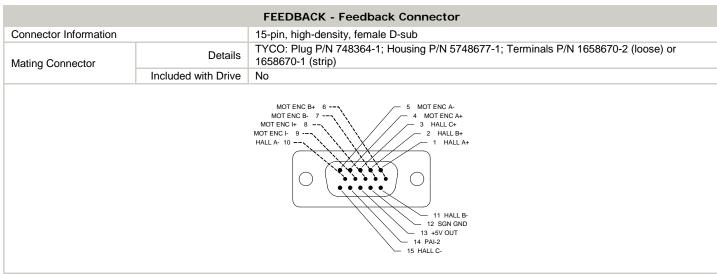
+24V LOGIC - Logic Power Connector		
Connector Information		2-port, 5.08 mm spaced, enclosed, friction lock header with threaded flange
Matina Commonton	Details	Phoenix Contact: P/N 1777808
Mating Connector	Included with Drive	Yes
		II I LOGIC GND 2 LOGIC PWR

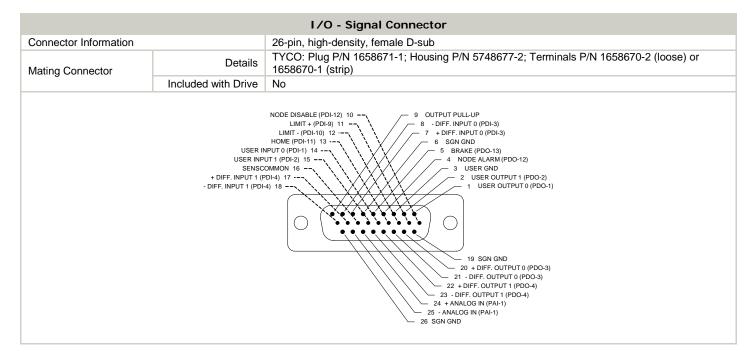
AUX COMM - RS232 Communication Connector		
Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
	Included with Drive	Yes
3 SGN GND 2 RS232 TX 1 RS232 RX		



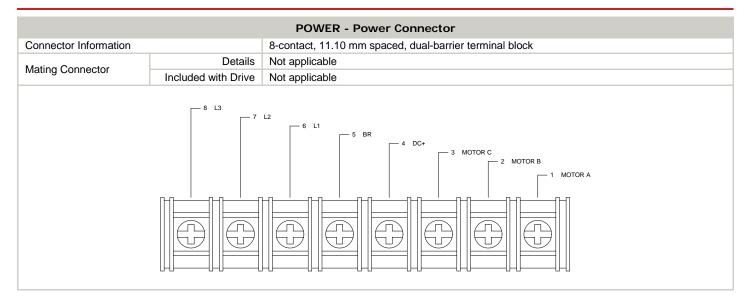






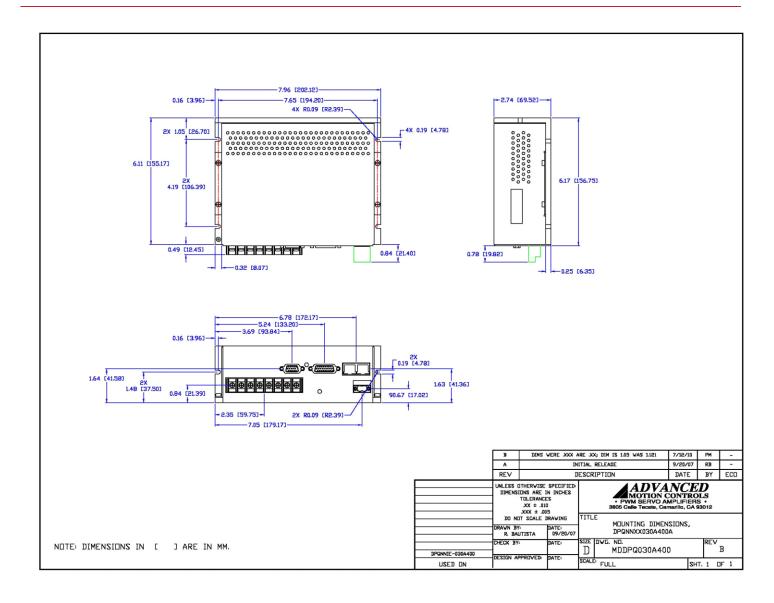






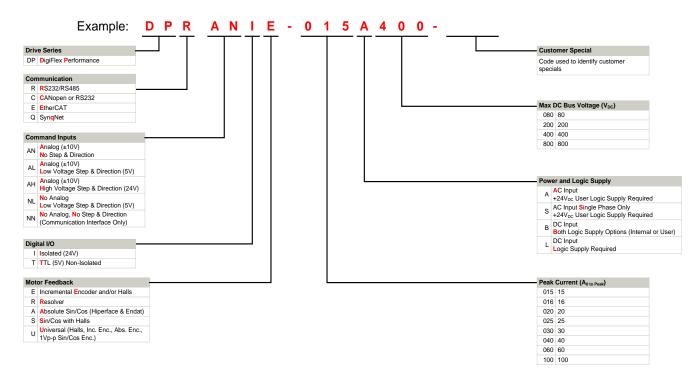


MOUNTING DIMENSIONS





PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ✓ No Outer Case
- ✓ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- Integrated System I/O

- ▲ Tailored Project File
- ▲ Silkscreen Branding
- Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.