

Description

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a SynqNet™ interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

Power Range	
Peak Current	25 A (17.7 A _{RMS})
Continuous Current	12.5 A (8.8 A _{RMS})
Supply Voltage	20 - 190 VDC



Features

- Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ✓ Fully Digital State-of-the-art Design

- Programmable Gain Settings
- ▲ 16-bit Analog to Digital Hardware

MODES OF OPERATION

Current

COMMAND SOURCE

Over the Network

FEEDBACK SUPPORTED

- Halls
- Incremental Encoder

INPUTS/OUTPUTS

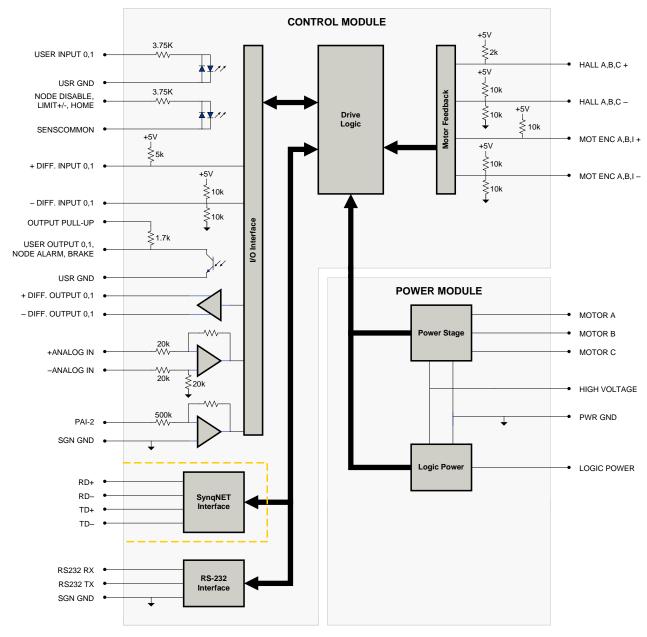
- 3 Dedicated Digital Inputs
- 2 Dedicated Digital Outputs
- 2 High Speed Captures
- 2 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 2 Programmable Digital Inputs (Differential)
- 2 Programmable Digital Inputs (Single-Ended)
- 2 Programmable Digital Outputs (Differential)
- 2 Programmable Digital Outputs (Single-Ended)

COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS



BLOCK DIAGRAM



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products. Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock. RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.



SPECIFICATIONS

Description	Power Specifications Description Units Value		
DC Supply Voltage Range	VDC	20 - 190	
DC Bus Over Voltage Limit	VDC	198	
DC Bus Under Voltage Limit	VDC	17	
Logic Supply Voltage	VDC	20 - 190	
Maximum Peak Output Current ¹	A (Arms)	25 (17.7)	
Maximum Continuous Output Current	A (Arms)	12.5 (8.8)	
Maximum Continuous Output Power	W	2256.3	
Maximum Power Dissipation at Continuous Current	W	118.8	
Internal Bus Capacitance	μF	50	
Minimum Load Inductance (Line-To-Line) ²	μH	300	
Switching Frequency	kHz	16	
Maximum Output PWM Duty Cycle	%	100	
Low Voltage Supply Outputs	-	+5 VDC (250 mA)	
	Control S	Specifications	
Description	Units	Value	
Communication Interfaces	-	SynqNet (RS-232 for configuration)	
Command Sources	-	Over the Network	
Feedback Supported	-	Halls, Incremental Encoder	
Commutation Methods	-	Sinusoidal, Trapezoidal	
Modes of Operation	-	Current	
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)	
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	4/2	
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	2/0	
Current Loop Sample Time	μs	62.5	
Maximum Encoder Frequency	MHz	5 (1.25 pre-quadrature)	
		I Specifications	
Description	Units	Value	
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
Size (H x W x D)	mm (in)	190.5 x 111.8 x 35.9 (7.5 x 4.4 x 1.4)	
Weight	g (oz)	872 (30.8)	
Heatsink (Base) Temperature Range ³	°C (°F)	0 - 75 (32 - 167)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Form Factor	-	Panel Mount	
Cooling System	-	Natural Convection	
IP Rating	-	IP10	
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header	
COMM IN Connector	-	Shielded RJ-45 socket with LEDs	
COMM OUT Connector	-	Shielded RJ-45 socket with LEDs	
FEEDBACK Connector	-	15-pin, high-density, female D-sub	
I/O Connector	-	26-pin, high-density, female D-sub	
MOTOR POWER Connector	-	3-port, 7.62 mm spaced, enclosed, friction lock header	
POWER Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header	

Notes

- Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements. Additional cooling and/or heatsink may be required to achieve rated performance.
- 2. 3.



PIN FUNCTIONS

	AUX COMM - RS232 Communication Connector		
Pin	Name	Description / Notes	1/0
1	RS232 RX	Receive Line (RS-232)	l I
2	RS232 TX	Transmit Line (RS-232)	0
3	SGN GND	Signal Ground	SGND

	COMM IN - SynqNet Communication Connector		
Pin	Name	Description / Notes	1/0
1	RD+	Pagaivar Lina (400PagaT)	I
2	RD-	Receiver Line (100BaseT)	I
3	TD+	Transmitter Line (100BaseT)	0
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	TD-	Transmitter Line (100BaseT)	0
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

	COMM OUT - SynqNet Communication Connector		
Pin	Name	Description / Notes	1/0
1	TD+	Transmitter Line (100BaseT)	0
2	TD-	Transmitter Line (100baser)	0
3	RD+	Receiver Line (100BaseT)	I
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RD-	Receiver Line (100BaseT)	I
7	RESERVED	Reserved	-
8	RESERVED	Reserved	-

		FEEDBACK - Feedback Connector	
Pin	Name	Description / Notes	1/0
1	HALL A+		I
2	HALL B+	Commutation Sensor Inputs	I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive	I
5	MOT ENC A-	Input)	I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive	I
7	MOT ENC B-	Input)	
8	MOT ENC I+	Differential Encoder Index Input / For Single Ended Signals Lies Only The Positive Input	I
9	MOT ENC I-	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	
14	PAI-2	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I



	I/O - Signal Connector		
Pin	Name	Description / Notes	1/0
1	USER OUTPUT 0 (PDO-1)	24V Isolated Programmable Digital Output (Referenced To USER GND)	0
2	USER OUTPUT 1 (PDO-2)	24V Isolated Programmable Digital Output (Referenced To USER GND)	0
3	USER GND	Ground Reference For User Outputs And Inputs	ISOGND
4	NODE ALARM (PDO-12)	24V Network Error (Isolated Output Referenced To USER GND)	0
5	BRAKE (PDO-13)	24V Brake (Isolated Output Referenced to USER GND)	0
6	SGN GND	Signal Ground	SGND
7	+ DIFF. INPUT 0 (PDI-3)	EV Non located Differential Digital Input	I
8	- DIFF. INPUT 0 (PDI-3)	5V Non-Isolated Differential Digital Input	I
9	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
10	NODE DISABLE (PDI-12)	24V Node Disable (Isolated Input Referenced to SENSCOMMON)	I
11	LIMIT + (PDI-9)	24V Positive Limit (Isolated Input Referenced To SENSCOMMON)	I
12	LIMIT - (PDI-10)	24V Negative Limit (Isolated Input Referenced To SENSCOMMON)	
13	HOME (PDI-11)	24V Home Switch (Isolated Input Referenced To SENSCOMMON)	
14	USER INPUT 0 (PDI-1)	24V Isolated Programmable Digital Input (Referenced To USER GND)	I
15	USER INPUT 1 (PDI-2)	24V Isolated Programmable Digital Input (Referenced To USER GND)	I
16	SENSCOMMON	Sensor Common (Can Be Used To Pull-Up Related Inputs)	CMN
17	+ DIFF. INPUT 1 (PDI-4)	FV Non Indiated Differential Digital Insuit	
18	- DIFF. INPUT 1 (PDI-4)	5V Non-Isolated Differential Digital Input	I
19	SGN GND	Signal Ground	SGND
20	+ DIFF. OUTPUT 0 (PDO-3)	EVAN-a la datad Differential Digital Outset	0
21	- DIFF. OUTPUT 0 (PDO-3)	5V Non-Isolated Differential Digital Output	0
22	+ DIFF. OUTPUT 1 (PDO-4)	EVAN-a la datad Differential Disital Outset	0
23	- DIFF. OUTPUT 1 (PDO-4)	5V Non-Isolated Differential Digital Output	
24	+ ANALOG IN (PAI-1)	AOV December Differential Academic (AC his December)	I
25	- ANALOG IN (PAI-1)	±10V Programmable Differential Analog Input (16-bit Resolution)	I
26	SGN GND	Signal Ground SG	

	MOTOR POWER - Power Connector		
Pin	Name	Description / Notes	I/O
1	MOTOR A	Motor Phase A	0
2	MOTOR B	Motor Phase B	0
3	MOTOR C	Motor Phase C	0

		POWER - Power Connector	
Pin	Name	Description / Notes	1/0
1	PWR GND	Power Ground (Common With Signal Ground)	PGND
2	2 HIGH VOLTAGE DC Power Input I		I
3	3 LOGIC GND Logic Supply Ground (Common With Signal Ground) GNI		GND
4	LOGIC PWR	Logic Supply Input	I



HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
Switch	Description	On	Off
1	Bit 0 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
7	Bit 6 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0
8	Bit 7 of binary SynqNet drive address. Does not affect RS-232 settings.	1	0

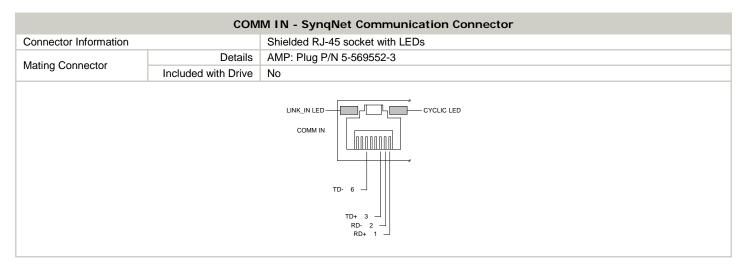
LED Functions

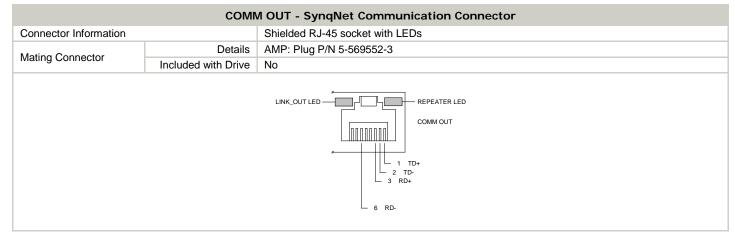
LED I MICHOID			
	LINK_IN LED		
On	Receive Valid		
Off	Not Valid or Power Off or Reset		
	CYCLIC LED		
On	Network Cyclic		
Off	Power Off or Reset		
Blinking	Network Not Cyclic		
LINK_OUT LED			
On	On Receive Valid		
Off	Not Valid or Power Off or Reset		
	REPEATER LED		
On	Repeater On, Network Cyclic		
Off	Repeater Off or Power Off or Reset		
Blinking	Repeater On, Network Not Cyclic		



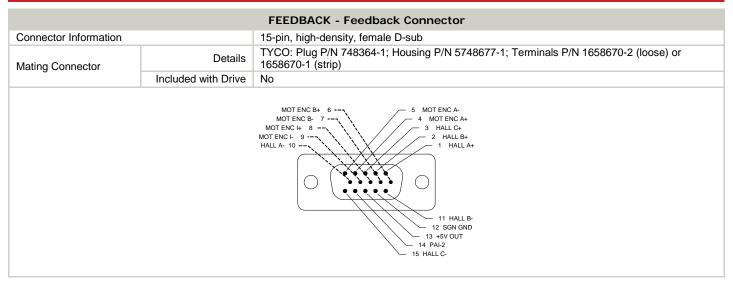
MECHANICAL INFORMATION

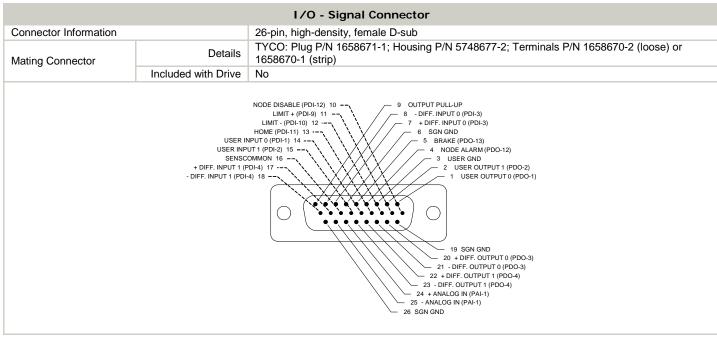
AUX COMM - RS232 Communication Connector		
Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
Mating Connector	Included with Drive	Yes
		3 SGN GND 2 RS232 TX 1 RS232 RX











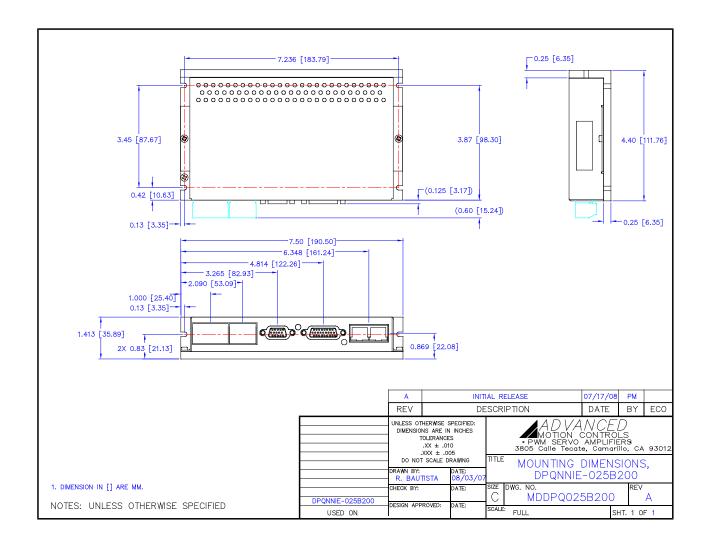
MOTOR POWER - Power Connector			
Connector Information		3-port, 7.62 mm spaced, enclosed, friction lock header	
Mating Connector	Details	Phoenix Contact: P/N 1804917	
	Included with Drive	Yes	
1 MOTOR A 2 MOTOR C			



DOWED Device Companies			
POWER - Power Connector			
Connector Information		4-port, 7.62 mm spaced, enclosed, friction lock header	
Mating Connector	Details	Phoenix Contact: P/N 1804920	
	Included with Drive	Yes	
	1 PWR GND 2 HIGH VOLTAGE 3 LOGIC GND 4 LOGIC PWR		

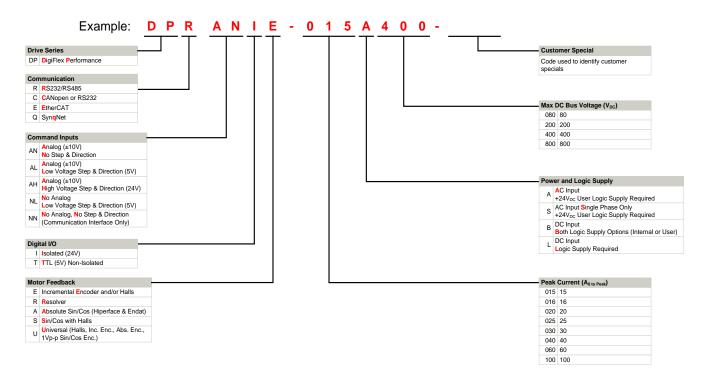


MOUNTING DIMENSIONS





PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

Examples of Customized Products

- Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ✓ No Outer Case
- ✓ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- Integrated System I/O

- ▲ Tailored Project File
- ▲ Silkscreen Branding
- Optimized Base Plate
- ✓ Increased Current Limits
- ▲ Increased Voltage Range
- Conformal Coating
- Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.