# BX15A SERIES BRUSHLESS SERVO AMPLIFIERS Model: BX15A20

#### **FEATURES:**

- Surface-mount technology
- Small size, low cost, ease of use
- DIP switch selectable: current, open loop, or tachometer velocity mode
- Four quadrant regenerative operation
- Agency Approvals:

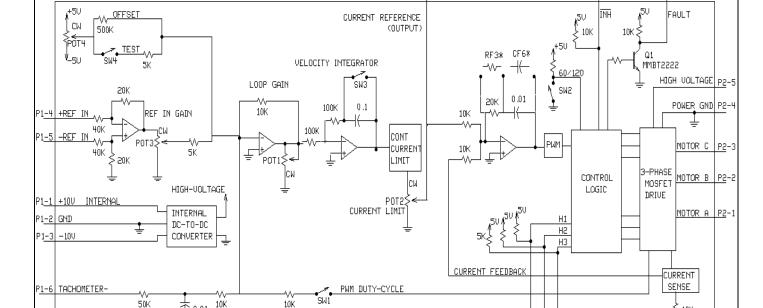
**BLOCK DIAGRAM:** 

P<u>1-7 TACHOMETER+</u>

FUNCTIONAL BLOCK DIAGRAM BX15A







P1-15

INTERNAL POWER-SUPPLY
FOR HALL SENSORS
.+VHall —

MODE SEL	ECTIO	N TAB	LE	
	SW1	SM2	SM3	SW4
CURRENT MODE	OFF	Х	ON	Х
TACHOMETER MODE	OFF	Х	OFF	Х
OPEN LOOP MODE	ON	Χ	OFF	Х
X-DOES NOT AFFECT MODE				

## **ADVANCED** MOTION CONTROLS

ALL 🛓 GROUNDS ARE INTERNALLY CONNECTED

0.01

3805 Calle Tecate, Camarillo, CA 93012 Tel: (805) 389-1935, Fax: (805) 389-1165

\* OPTIONAL USER INSTALLED

THROUGH HOLE COMPONENT

≶10K

HALL SENSORS

CURRENT

MONITOR

**DESCRIPTION:** The BX15A Series PWM servo amplifiers are designed to drive brushless DC motors at a high switching frequency. A single red/green LED indicates operating status. BX15A Series amplifiers are fully protected against over-voltage, over-current, over-heating and short-circuits. They interface with a digital controller or can be used as a stand-alone drive. These models requires only a single unregulated DC power supply. Loop gain, current limit, input gain and offset can be adjusted using 14-turn potentiometers. The offset adjusting potentiometer can also be used as an on-board input signal for testing purposes, when SW4 (DIP switch) is ON.

## **SPECIFICATIONS:**

	MODEL
POWER STAGE SPECIFICATIONS	BX15A20
DC SUPPLY VOLTAGE	40-190 V
PEAK CURRENT (2 sec. maximum)	± 15 A
MAXIMUM CONTINUOUS CURRENT	± 7.5 A
MINIMUM LOAD INDUCTANCE*	250 μΗ
SWITCHING FREQUENCY	$26~\mathrm{kHz}\pm15\%$
HEATSINK (BASE) TEMPERATURE RANGE	0° to + 65° C, disables if > 65° C
POWER DISSIPATION AT CONTINUOUS CURRENT	75 W
OVER-VOLTAGE SHUT-DOWN (self reset)	195 V
BANDWIDTH (load dependent)	2.5 kHz

MECHANICAL SPECIFICATIONS				
POWER CONNECTOR	Screw terminals			
SIGNAL CONNECTOR	Molex connector			
SIZE	5.09 x 3.48 x 0.99 inches			
SIZE	129.3 x 88.5 x 25.1 mm			
WEIGHT	12 oz.			
WEIGHT	.33 kg			

<sup>\*</sup> Low inductance motors require external inductors.

# **PIN FUNCTIONS:**

CONNECTOR	PIN	NAME	DESCRIPTION / NOTES	I/O
	1	+10V @ 3 mA OUT	For customer use	0
	2	SIGNAL GND	Reference ground	GND
	3	-10V @ 3 mA OUT	For customer use	0
	4	+REF IN	Differential reference input, maximum ±15 V,	1
	5	-REF IN	40K input resistance	
	6	-TACH IN	Tachometer input, max. ±60 VDC, 60K input resistance	I
	7	+TACH / GND	Ground	
	8	CURRENT MONITOR OUT	Current monitor. 1 V = 2.28 A	
P1	9	INHIBIT IN	This TTL level input signal turns off all power devices of the "H" bridge when pulled to ground. This inhibit will cause a fault condition and a red LED. For inverted inhibit input, see section "G".	
	10	+V HALL OUT	Power for HALL sensors, short circuit protected, +6 V @ +30 mA.	0
	11	GND	+0 V @ +30 MA.	GND
	12	HALL 1	HALL sensor inputs, TTL logic levels, internal 5 KΩ	1
	13	HALL 2	pull-up. Maximum low level input is 1.5 V, minimum high level input is 3.5 V	
	14	HALL 3	- minimum mg.merer in pacie ele v	
	15	CURRENT REFERENCE OUT	Monitors the input signal connected directly to the internal current amplifier. 7.25 V = max current. See current limit adjustment information below.	0
	16	FAULT OUT (red LED)	TTL level output. Becomes high during output short circuit, over-voltage, inhibit, over-temperature and during power-on reset. Fault condition indicated by red LED.	0
	1	MOTOR A	Motor phase A connection	0
	2	MOTOR B	Motor phase B connection	0
P2	3	MOTOR C	Motor phase C connection	0
	4	POWER GND	Power ground	GND
	5	HIGH VOLTAGE	DC power input	I

# **SWITCH FUNCTIONS:**

		SETTING		
SWITCH	FUNCTION DESCRIPTION	ON	OFF	
1	Duty-cycle feedback	Open Loop	No Effect	
2	60 / 120 degree commutation phasing setting	120 degree	60 degree	
3	Loop integrator. This capacitor normally ensures "error-free" operation in velocity mode by reducing the error-signal (output of summing amplifier) to zero.	Shorts out the velocity / voltage loop integrator capacitor.	Velocity / voltage loop integrator capacitor operating.	
4	Test / Offset. Sensitivity of the "offset" pot. Used as an on-board reference signal in test mode.	Test	Offset	

# **POTENTIOMETER FUNCTIONS:**

POTENTIOMETER	DESCRIPTION	TURNING CW
Pot 1	Loop gain adjustment in open loop & velocity modes. Turn this pot fully ccw in current mode.	Increases loop gain
Pot 2	Current limit. It adjusts both continuous and peak current limit while maintaining their ratio (50%).	Increases current limit
Pot 3	Reference gain. It adjusts the ratio between input signal and output variables (voltage, current, velocity).	Increases reference input gain
Pot 4	Test / Offset. Used to adjust any imbalance in the input signal or in the amplifier. When SW4 (DIP switch) is ON, the sensitivity of this pot is greatly increased thus it can be used as an on-board signal source for testing purposes. See section "G".	N/A

### **OPERATING MODE SELECTION:**

These modes can be selected by the DIP switches according to the chart in the functional block diagram:

- Current mode
- Open loop mode
- Tachometer mode

See section "G" for more information.

#### SET-UP:

See section "G" for engineering and installation notes.

## **CURRENT LIMIT ADJUSTMENTS:**

These amplifiers feature peak and continuous current limit adjustments. Potentiometer 2, the current limiting potentiometer, has 12 active turns plus 1 inactive turn at each end and is approximately linear. Thus, to adjust the current limit turn the potentiometer fully counter-clockwise, then turn clockwise to the appropriate value.

P1-15 is the input to the internal current amplifier stage. Since the output current is proportional to P1-15, the adjusted current limit can easily be observed at this pin without connecting the motor. Note that a command signal must be applied to the reference inputs to obtain a reading on P1-15. The maximum peak current value equals 7.25 V at this pin and the maximum continuous current value equals 3.63 V at this pin. Example: Using the BX15A20, 7.25V=15A.

The actual current can be monitored at pin P1-8.

TYPICAL SYSTEM WIRING: See section "G".

### **ORDERING INFORMATION:**

Model: BX15A20X

X (at the end) indicates the current revision letter.

**MOUNTING DIMENSIONS:** See page F-32.

