

Description

The BD30A8 PWM servo drive is designed to drive brushless DC motors at a high switching frequency. It is fully protected against over-voltage, over-current, over-heating and short-circuits. The drive interfaces with digital controllers that have a digital PWM output. PWM IN determines the output duty cycle. DIR IN determines the direction of rotation. A single red/green LED indicates operating status. The current limit can be set by DIP switches.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range

| | |
|--------------------|-------------|
| Peak Current | 30 A |
| Continuous Current | 15 A |
| Supply Voltage | 20 - 80 VDC |



Features

- ▲ Four Quadrant Regenerative Operation
- ▲ Optically Isolated Digital Inputs
- ▲ Adjustable Current Limits
- ▲ High Switching Frequency
- ▲ Digital Fault Output Monitor
- ▲ Selectable 120/60 Hall Commutation Phasing
- ▲ Drive Status LED

MODES OF OPERATION

- Direct PWM

COMMAND SOURCE

- PWM and Direction

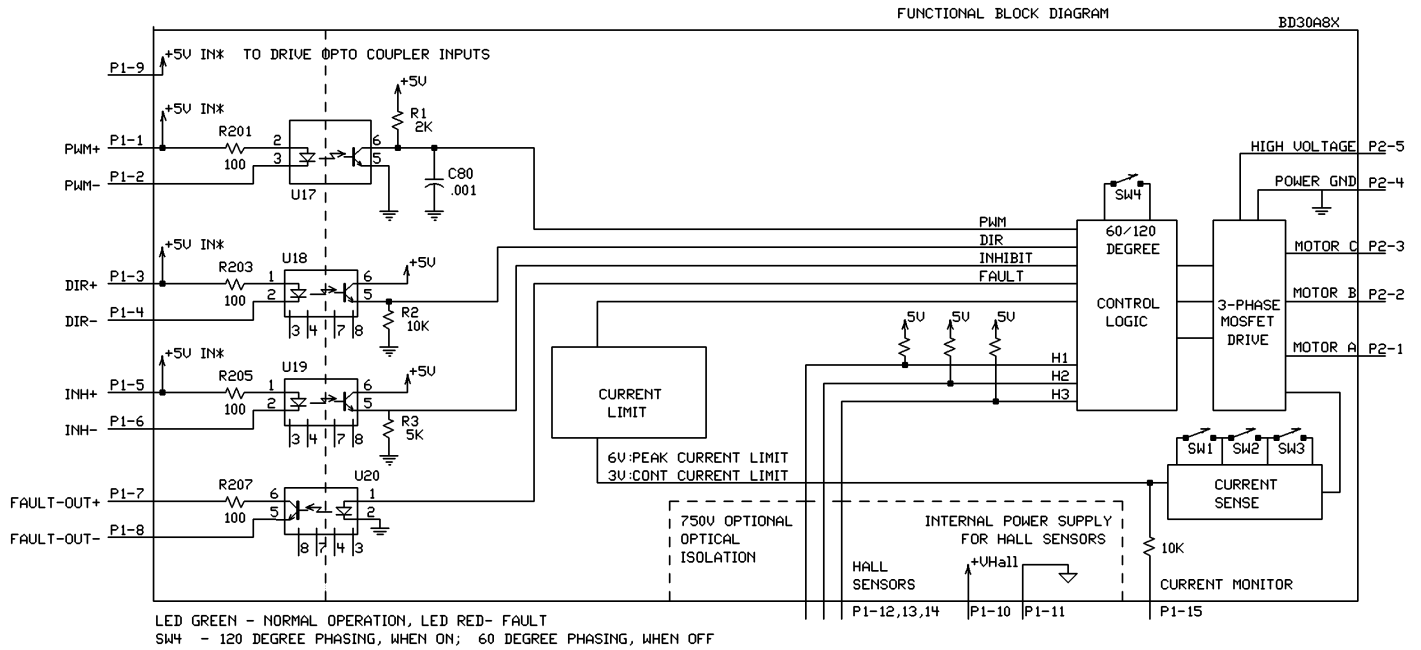
FEEDBACK SUPPORTED

- Halls




COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

BLOCK DIAGRAM



Information on Approvals and Compliances

| | |
|---|---|
|  | <p>US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.</p> |
|  | <p>Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.</p> |
|  | <p>RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.</p> |

SPECIFICATIONS

| Power Specifications | | |
|---|---------|--|
| Description | Units | Value |
| DC Supply Voltage Range | VDC | 20 - 80 |
| DC Bus Over Voltage Limit | VDC | 86 |
| Maximum Peak Output Current ¹ | A | 30 |
| Maximum Continuous Output Current | A | 15 |
| Maximum Continuous Output Power | W | 1140 |
| Maximum Power Dissipation at Continuous Current | W | 60 |
| Minimum Load Inductance (Line-To-Line) ² | µH | 200 |
| Low Voltage Supply Outputs | - | ±6 VDC (30 mA) |
| Switching Frequency Range | kHz | 5 - 20 |
| Control Specifications | | |
| Description | Units | Value |
| Command Sources | - | PWM and Direction |
| Feedback Supported | - | Halls |
| Commutation Methods | - | Trapezoidal |
| Modes of Operation | - | Direct PWM |
| Motors Supported | - | Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless) |
| Hardware Protection | - | Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Short Circuit (Phase-Phase & Phase-Ground) |
| Primary I/O Logic Level | - | 5V TTL |
| Mechanical Specifications | | |
| Description | Units | Value |
| Agency Approvals | - | CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL |
| Size (H x W x D) | mm (in) | 186.7 x 111.7 x 25.4 (7.4 x 4.4 x 1) |
| Weight | g (oz) | 680 (24) |
| Heatsink (Base) Temperature Range ³ | °C (°F) | 0 - 65 (32 - 149) |
| Storage Temperature Range | °C (°F) | -40 - 85 (-40 - 185) |
| Form Factor | - | Panel Mount |
| P1 Connector | - | 16-pin, 2.54 mm spaced, friction lock header |
| P2 Connector | - | 5-port, 5.08 mm spaced, screw terminal |

Notes

1. Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.
2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
3. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

| P1 - Signal Connector | | | |
|-----------------------|------------------|---|-----|
| Pin | Name | Description / Notes | I/O |
| 1 | +PWM | Opto-isolated Pulse Width Modulation Input. Positive input internally connected to P1-9. | I |
| 2 | -PWM | Ground negative input to activate. Activating opto-couple activates bridge output. | I |
| 3 | +DIR | Opto-isolated Direction Input. Positive input internally connected to P1-9. Ground negative input to activate. Activating opto-couple activates bridge output. | I |
| 4 | -DIR | | I |
| 5 | +INHIBIT | Opto-isolated Inhibit Input. Positive input internally connected to P1-9. Ground negative input to activate. Activating opto-couple activates bridge output. | I |
| 6 | -INHIBIT | | I |
| 7 | +FAULT | Opto-isolated Fault Output (+5 V). Output transistor turns on during output short circuit, over voltage, over temperature, inhibit, invalid Hall state, and during power-up reset. Fault condition indicated by red LED. | O |
| 8 | -FAULT | | O |
| 9 | +5V IN | +5 V (at least 150 mA) input to drive opto-isolated inputs. | I |
| 10 | +V HALL OUT | | O |
| 11 | GND | Low Power Supply For Hall Sensors (+6 V @ 30 mA). Short circuit protected. | GND |
| 12 | HALL 1 | | I |
| 13 | HALL 2 | Single-ended Hall/Commutation Sensor Inputs (+5 V logic level) | I |
| 14 | HALL 3 | | I |
| 15 | CURR MONITOR OUT | Current Monitor. Analog output signal proportional to the actual current output. Scaling is 4 A/V by default but may be reduced by DIP switch settings (see Hardware Settings section below). Measure relative to power ground. | O |
| 16 | NC | Not Connected (Reserved) | - |

| P2 - Power Connector | | | |
|----------------------|--------------|--|------|
| Pin | Name | Description / Notes | I/O |
| 1 | MOTOR A | Motor Phase A | O |
| 2 | MOTOR B | Motor Phase B | O |
| 3 | MOTOR C | Motor Phase C | O |
| 4 | POWER GND | Power Ground (Isolated From Signal Ground) | PGND |
| 5 | HIGH VOLTAGE | DC Power Input | I |

HARDWARE SETTINGS

Switch Functions

| Switch | Description | Setting | |
|--------|--|-------------|------------|
| | | On | Off |
| 1 | Bit 0 of the current limit setting. See details below. | 1 | 0 |
| 2 | Bit 1 of the current limit setting. See details below. | 1 | 0 |
| 3 | Bit 2 of the current limit setting. See details below. | 1 | 0 |
| 4 | 60/120 degree commutation phasing setting | 120 degrees | 60 degrees |

Additional Details

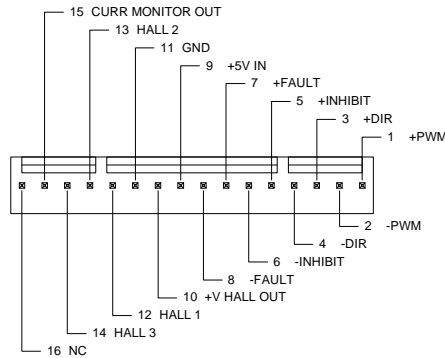
Switches 1, 2 and 3 can be used to reduce the peak and continuous current limit to a percentage given in the table below. 100% means no reduction.

| Current Limit % | Current Monitor Scaling (A/V) | Switch Setting | | |
|-----------------|-------------------------------|----------------|----------|----------|
| | | Switch 3 | Switch 2 | Switch 1 |
| 12.5 | 0.5 | OFF | OFF | OFF |
| 25 | 1 | OFF | OFF | ON |
| 50 | 2 | OFF | ON | ON |
| 100 | 4 | ON | ON | ON |

MECHANICAL INFORMATION

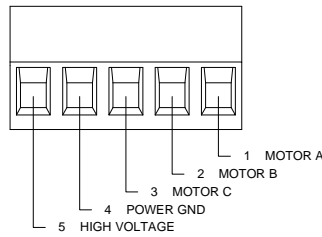
P1 - Signal Connector

| | | |
|-----------------------|---------------------|---|
| Connector Information | | 16-pin, 2.54 mm spaced, friction lock header |
| Mating Connector | Details | Molex: P/N 22-01-3167 (connector) and P/N 08-50-0114 (insert terminals) |
| | Included with Drive | Yes |

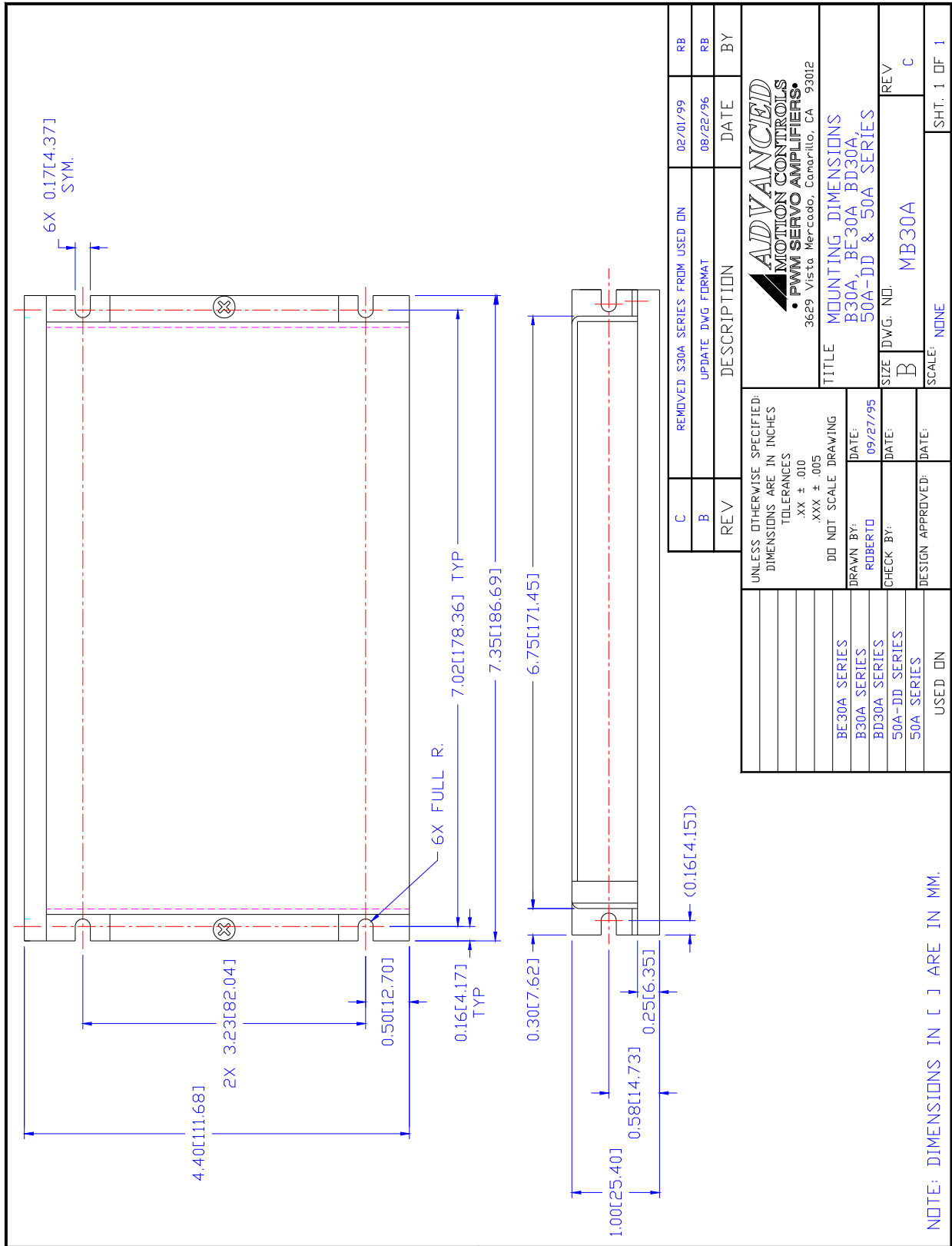


P2 - Power Connector

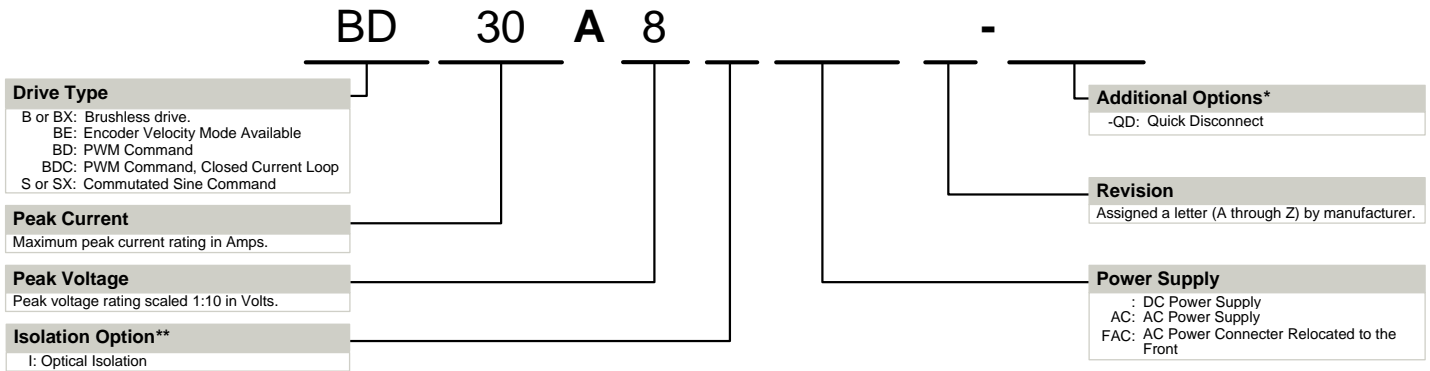
| | | |
|-----------------------|---------------------|--|
| Connector Information | | 5-port, 5.08 mm spaced, screw terminal |
| Mating Connector | Details | Not applicable |
| | Included with Drive | Not applicable |



MOUNTING DIMENSIONS



PART NUMBERING INFORMATION



* Options available for orders with sufficient volume. Contact *ADVANCED* Motion Controls for more information.
 ** Isolation comes standard on all AC supply drives and most DC supply drives 200V and above. Consult selection tables of the website or drive datasheet block diagram to see if isolation is included.

ADVANCED Motion Controls analog series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, *ADVANCED* Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

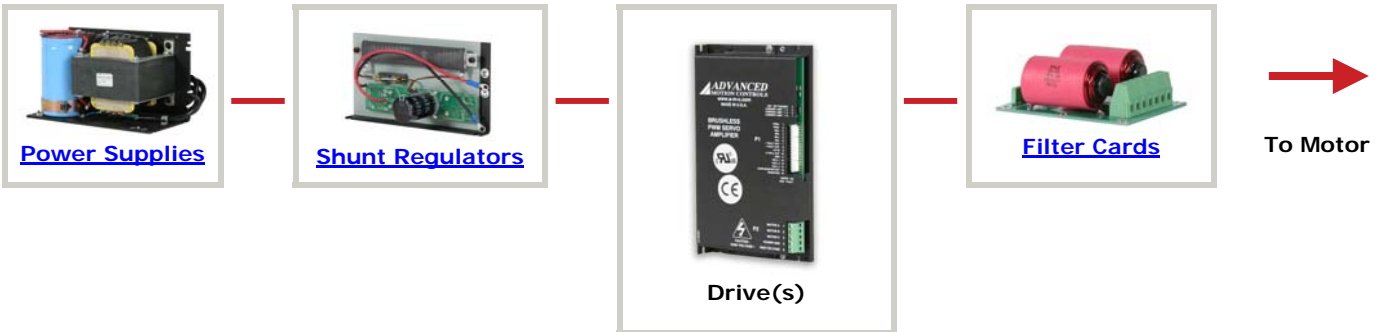
Examples of Modifications and Customized Products

- | | |
|---|--|
| <ul style="list-style-type: none"> ▲ Integration of Drive into Motor Housing ▲ Mount OEM PCB onto Drive Without Cables ▲ Multi-axis Configuration for Compact System ▲ Custom PCB and Baseplate for Optimized Footprint ▲ RTV/Epoxy Components for High Vibration ▲ OEM Specified Connectors for Instant Compatibility ▲ OEM Specified Silkscreen for Custom Appearance ▲ Increased Thermal Limits for High Temp. Operation | <ul style="list-style-type: none"> ▲ Integrate OEM Circuitry onto Drive PCB ▲ Custom Control Loop Tuned to Motor Characteristics ▲ Custom I/O Interface for System Compatibility ▲ Preset Switches and Pots to Reduce User Setup ▲ Optimized Switching Frequency ▲ Ramped Velocity Command for Smooth Acceleration ▲ Remove Unused Features to Reduce OEM Cost ▲ Application Specific Current and Voltage Limits |
|---|--|

Feel free to contact Applications Engineering for further information and details.

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.