## BD30A SERIES BRUSHLESS SERVO AMPLIFIERS <br> Models: BD30A8, BD25A20

## FEATURES:

- Surface-mount technology
- Small size, low cost, ease of use
- Input signal isolation
- Four quadrant regenerative operation
- Hall sensor commutation
- Agency Approvals:



## BLOCK DIAGRAM:



ADVANCED MOTION CONTROLS
3805 Calle Tecate, Camarillo, CA 93012 Tel: (805) 389-1935, Fax: (805) 389-1165

DESCRIPTION: The BD30A Series PWM servo amplifiers are designed to drive brushless DC motors at a high switching frequency. They are fully protected against over-voltage, over-current, over-heating and short-circuits. All models interface with digital controllers that have a digital PWM output. PWM IN determines the output duty cycle. DIR IN determines the direction of rotation. A single red/green LED indicates operating status. The current limit can be set by DIP switches.

## SPECIFICATIONS:

|  | MODELS |  |
| :---: | :---: | :---: |
| POWER STAGE SPECIFICATIONS | BD30A8 | BD25A20 |
| DC SUPPLY VOLTAGE | 30-80 V | 40-190 V |
| PEAK CURRENT (2 sec. max., internally limited) | $\pm 30 \mathrm{~A}$ | $\pm 25 \mathrm{~A}$ |
| MAX. CONTINUOUS CURRENT (internally limited) | $\pm 15 \mathrm{~A}$ | $\pm 12.5 \mathrm{~A}$ |
| MINIMUM LOAD INDUCTANCE* | $200 \mu \mathrm{H}$ | $250 \mu \mathrm{H}$ |
| SWITCHING FREQUENCY | $5-20 \mathrm{kHz} \pm 15 \%$ |  |
| HEATSINK (BASE) TEMPERATURE RANGE | $0^{\circ}$ to $+65^{\circ} \mathrm{C}$, disables if $>65^{\circ} \mathrm{C}$ |  |
| POWER DISSIPATION AT CONT. CURRENT | 60 W | 125 W |
| OVER-VOLTAGE SHUT-DOWN (self reset) | 86 V | 195 V |


| MECHANICAL SPECIFICATIONS |  |
| :--- | :---: |
| POWER CONNECTOR | Screw terminals |
| SIGNAL CONNECTOR | Molex connector |
| SIZE | $7.35 \times 4.40 \times 1.00$ inches |
|  | $186.7 \times 111.7 \times 25.4 \mathrm{~mm}$ |
|  | 1.5 lb. |
|  | 0.68 kg |

[^0]
## PIN FUNCTIONS:

| CONNECTOR | PIN | NAME | DESCRIPTION / NOTES | I/O |
| :---: | :---: | :---: | :---: | :---: |
| P1 | 1 | PWM + | Same as pin 9 | 1 |
|  | 2 | PWM- | Pulse width modulated digital input | 1 |
|  | 3 | DIR+ | Same as pin 9 | 1 |
|  | 4 | DIR- | Direction input | 1 |
|  | 5 | INH+ | Same as pin 9 | 1 |
|  | 6 | INH- | Pull low to enable | 1 |
|  | 7 | +FAULT | Output transistor turns on and becomes high during output short circuit, over-voltage, over temperature, inhibit, and during power-up reset. Fault condition indicated by red LED. | 0 |
|  | 8 | -FAULT |  |  |
|  | 9 | +5 IN | +5V @ 150 mA in to drive opto coupler inputs. | 1 |
|  | 10 | +V HALL OUT | Power for HALL sensors, Short circuit protected, + 6 V @ 30 mA . See optical signal isolation option below. | 0 |
|  | 11 | GND |  | GND |
|  | 12 | HALL 1 | HALL sensor inputs, logic levels, internal $5 \mathrm{~K} \Omega$ pullup. Maximum low level input is 1.5 V , Minimum high level input is 3.5 V . See optical signal isolation option below. | 1 |
|  | 13 | HALL 2 |  |  |
|  | 14 | HALL 3 |  |  |
|  | 15 | CURRENT MONITOR OUT | Current monitor. This signal is proportional to the actual current in the motor leads. See current limit adjustments section below for scaling. | O |
|  | 16 | Reserved |  |  |
| P2 | 1 | MOTOR A | Motor phase A connection | 0 |
|  | 2 | MOTOR B | Motor phase B connection | $\bigcirc$ |
|  | 3 | MOTOR C | Motor phase C connection | $\bigcirc$ |
|  | 4 | POWER GND | Power ground | GND |
|  | 5 | HIGH VOLTAGE | DC power input | 1 |

SET-UP: See section "G" for engineering and installation notes.

## CURRENT LIMIT ADJUSTMENTS:

These amplifiers feature peak and continuous current limit adjustments. DIP switches reduce both peak and continuous current limit. The ratio of peak/continuous current limit is fixed ( $50 \%$ ). The switches also adjust the scaling of CURRMONITOR output.

| sW1 | sW2 | SW3 | Peak current <br> (\% of max.) | Continuous current <br> (\% of max. cont.) | Current Monitor Scaling |
| :---: | :---: | :---: | :---: | :---: | :---: |
| ON | ON | ON | $100 \%$ | $100 \%$ | $4 \mathrm{~A} / \mathrm{V}$ |
| ON | ON | OFF | $50 \%$ | $50 \%$ | $2 \mathrm{~A} / \mathrm{V}$ |
| ON | OFF | OFF | $25 \%$ | $25 \%$ | $1 \mathrm{~A} / \mathrm{V}$ |
| OFF | OFF | OFF | $12.5 \%$ | $12.5 \%$ | $0.5 \mathrm{~A} / \mathrm{V}$ |

The actual current can be monitored at pin P1-15 and is referenced to POWER GND P2-4.

## OPTICAL INPUT SIGNAL ISOLATION:

PWM, DIR, INH, FAULT inputs are always isolated from the power section. If the isolation option is selected the Hall sensor inputs (P1-10 through 14) are also isolated. If the isolated version is not ordered, an isolated power supply should be used with this series of amplifiers.

## ORDERING INFORMATION:

Models: BD30A8X, BD25A20X
With isolation:
Models: BD30A8IX, BD25A20IX
$X$ indicates the current revision letter.

MOUNTING DIMENSIONS: See page F-9.



[^0]:    * Low inductance motors require external inductors.

